

# Color Image Segmentation

based on

## Automatic Morphological Clustering

T. Géraud, P.-Y. Strub, J. Darbon

`thierry.geraud@lrde.epita.fr`



# Outline

- Introduction
  - about statistical classification
  - about watershed algorithm
  - problem statement
- Morphological classification
  - state of the art
  - description of proposed approach
  - commented results
- Conclusion

# A classical statistical and non-contextual classification scheme

- Transform observations into feature vectors
  - for a pixel, a feature can be a color component, a local variance...
  - difficulty: find a relevant feature space
- In feature space
  - assign / learn a parametric model for each class
  - then run a classifier

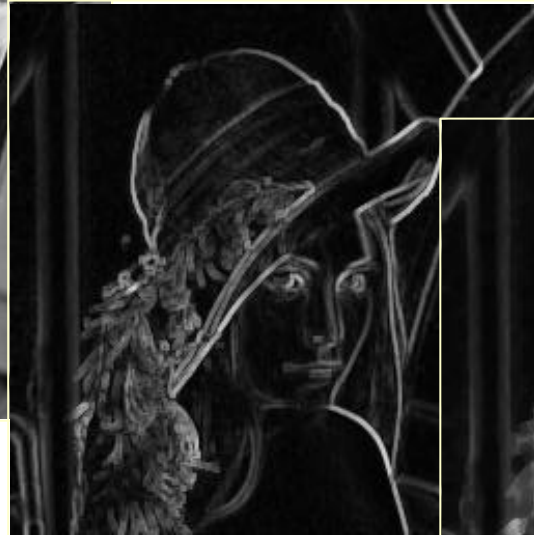
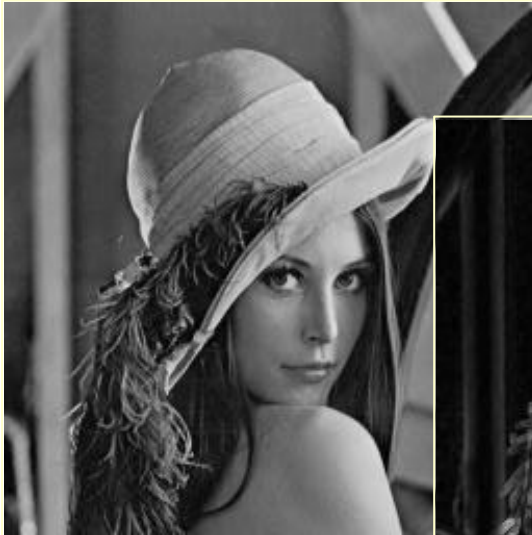
Remark:

the *probability density function* of a class in the feature space can be estimated from few samples; e.g., convolve the samples with a Gaussian kernel

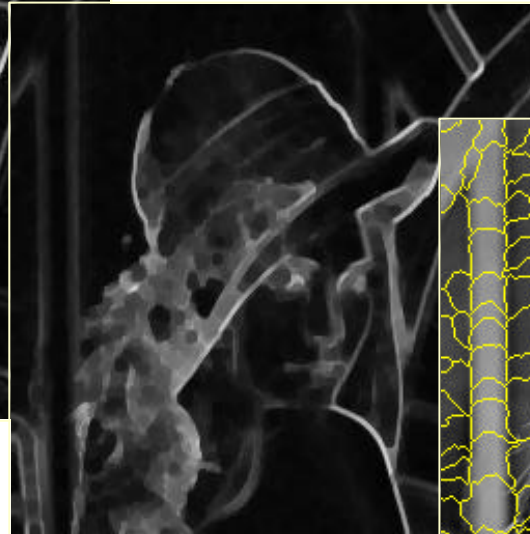
# About watershed algorithm

- Key features
  - it applies on  $n$ - $D$  images
  - the algorithm divides the input image into regions (*basins*)
  - one local minimum leads to one surrounding basin
  - a 1-pixel thick component (*watershed*) separates every basins
  - basin boundaries are located on image crest values
- Connected version of the algorithm
  - the watershed itself is suppressed
  - other properties are maintained
  - as output image we get a partition
- A reliable segmentation tool
  - “*Scale-Space Segmentation of Color Images Using Watersheds and Fuzzy Region Merging*,” by Makrogiannis *et al.*, ICIP 2001

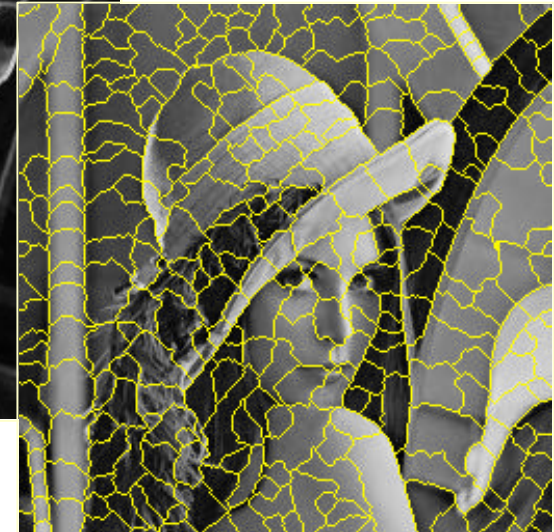
# A classical morphological segmentation method



morphological gradient  
*(high values correspond to object contours)*



morphological closing  
*(the number of local minima is reduced)*



morphological watershed algorithm  
*(the watershed is located on object contours)*

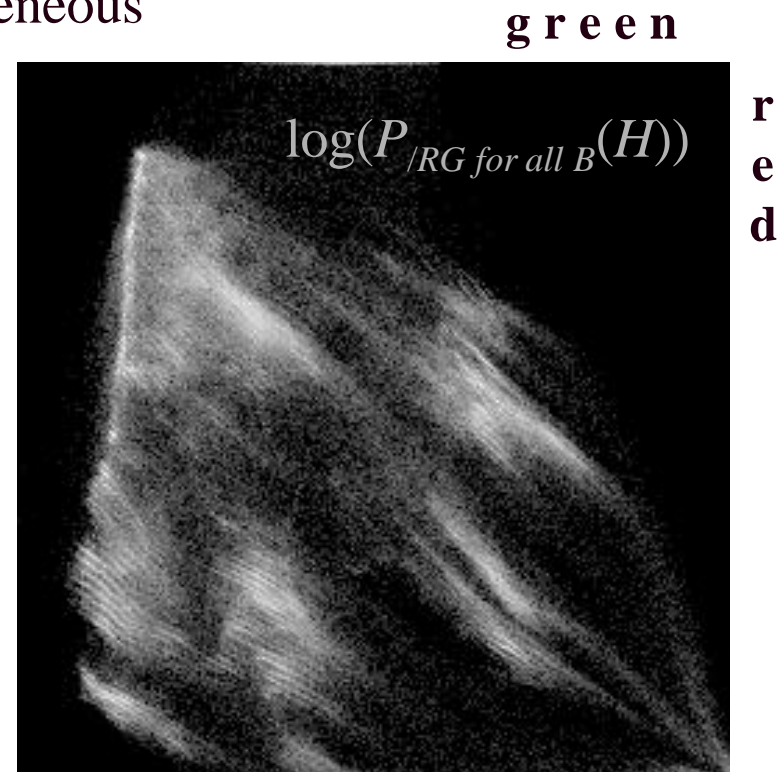
# Problem statement

- Color images

- feature space is (at least) 3-dimensional
- in such a space, clusters have low-density
- cluster cardinalities are very heterogeneous
- many artifacts appear due to:
  - storage compression
  - color gradations
  - specular surface of objects

- Statistical models

*are they relevant?*



# Morphological classification of color images (state of the art)

- Basic idea:

RGB image → compute histogram = 3D image  
→ morphological cluster identification

- ♦ Postaire *et al.*, “Cluster Analysis by Binary Morphology”, PAMI 15(2).
- ♦ Zang *et al.*, “Convexity Dependent Morphological transformations for Mode Detection in Cluster Analysis,” Pattern Recognition 27(1).
- ♦ Park *et al.*, “Color Image Segmentation Based on 3D Clustering: Morphological Approach,” Pattern Recognition 31(8).

- Drawbacks:

→ clusters should be prominent and well-contrasted  
→ only cluster cores are segmented; so, how to handle color *outliers*?

# Morphological classification

presented here 

- From a color image:
  - express data in feature space
    - for instance, a 3-D RGB histogram
  - consider data as a  $n$ -D image
  - regularize data
  - run a *morphological partitioning*
- Originality:  
*use of the watershed algorithm as a classifier*



# Method details

Step	Description	<i>Rationale</i>
.....		
1	data computation in feature space, log transform, and inversion	<i>get a grey-level image <math>H</math> where clusters have dark values</i>
2	Gaussian filtering	<i>regularize (while suppressing many local minima)</i>
3	closing plus cutting low values	<i>suppress extra local minima</i>
4	connected watershed algorithm	<i>get a partition <math>W</math> of feature space</i>
5	apply a segmentation process...	

# Method properties

- Applying an increasing function  $f$  to feature space values (densities):

$$H_{bis}(c) = f(H(c)) \Rightarrow W_{bis}(c) = W(c)$$

- Applying a rigid transform  $T$  to features:

$$H_{bis}(c') = H(T(c)) \Rightarrow W_{bis}(c') = W(T(c))$$

- Applying a scaling factor  $\alpha$  to a given feature:

$$H_{bis}(c_1, c'_2) = H(c_1, \alpha c_2) \Rightarrow W_{bis}(c_1, c'_2) = W(c_1, \alpha c_2)$$

# Some segmentation approaches

(step 5)

- Using directly feature space partitioning:
  - segmentation = *non contextual labeling*
  - but a feature can be contextual (e.g., a local variance)
- Considering that we can learn from feature space classes...

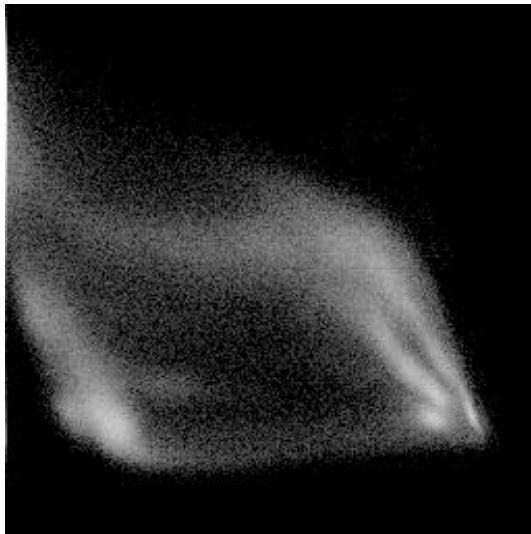
for example, perform a *Bayesian labeling*:

- estimate Mahalanobis distances from basins
- run a Markovian relaxation in image domain

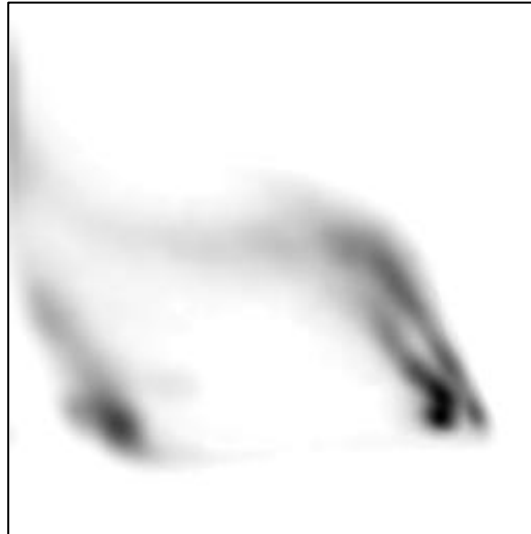
# Segmentation results

(on peppers image)

Projections on the RG plane of 3D data:

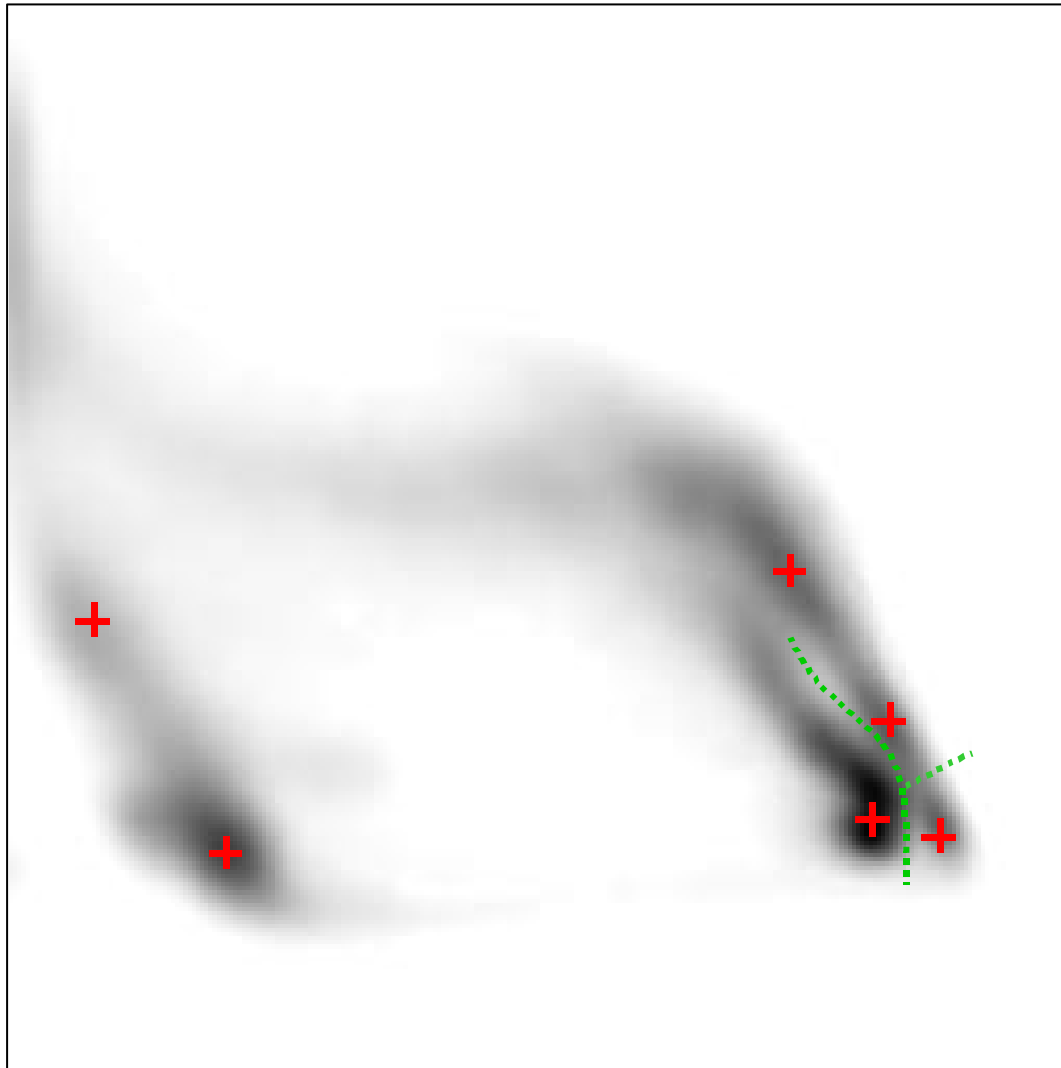


$\log( P_{/RG}(H) )$



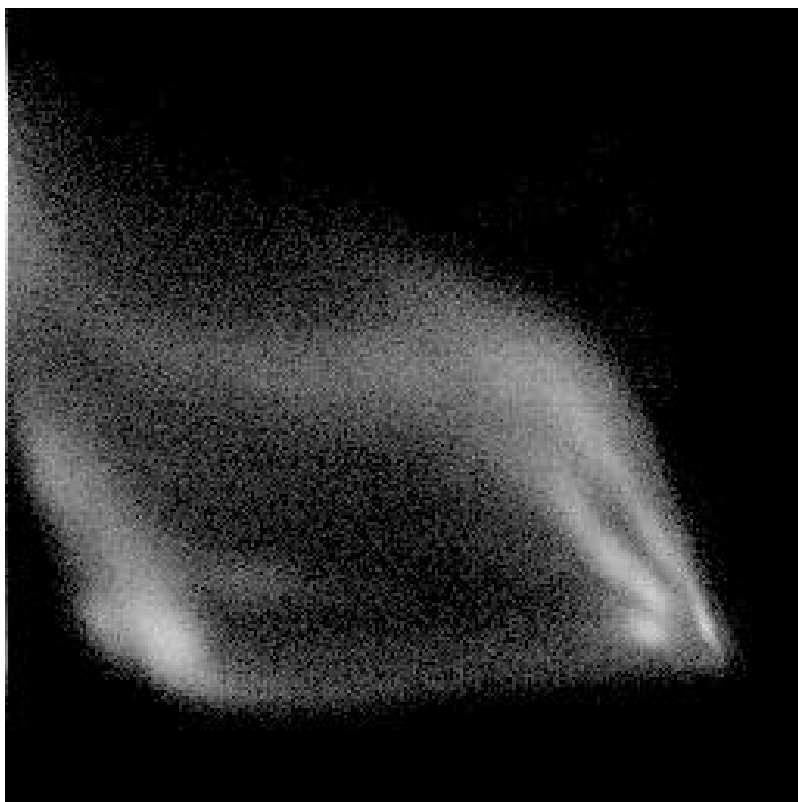
result of step 3

= input of the watershed  
algorithm

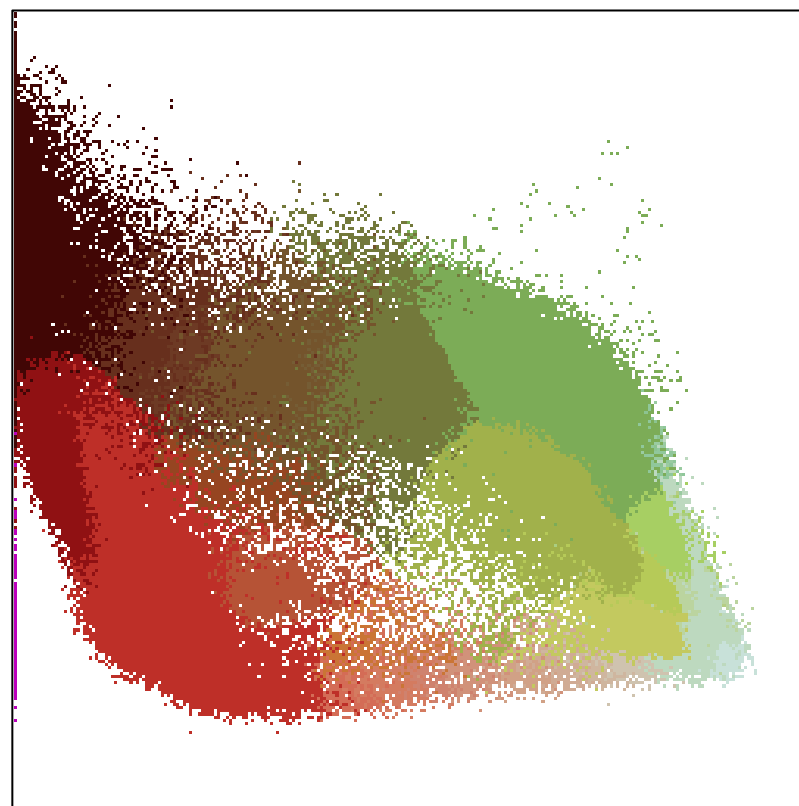


+	local minima
.....	basin boundary

result of step 3



$\log( P_{/RG}(H) )$



classes

## Non-contextual labeling



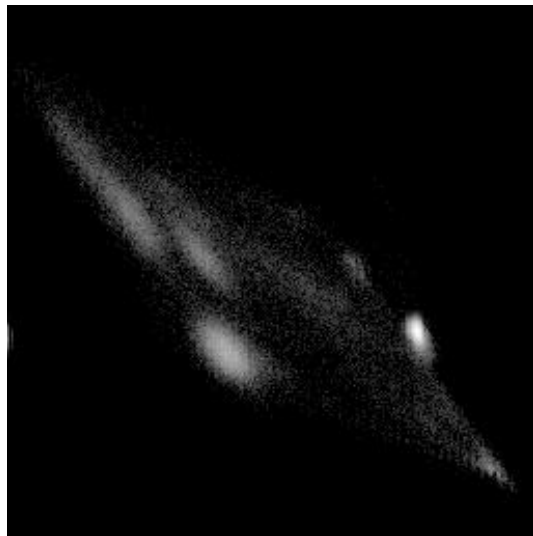


## Markovian labeling

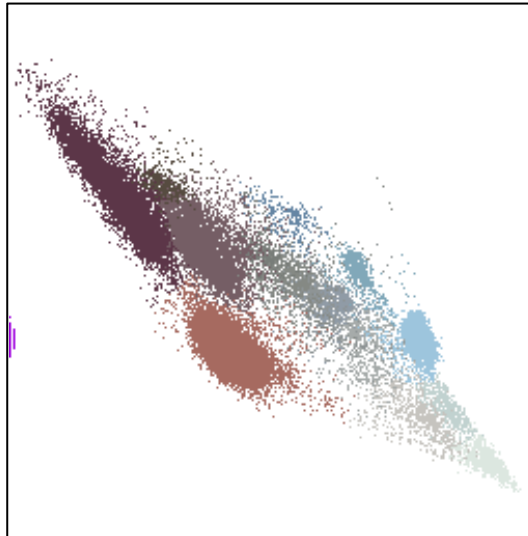




# Other results



$\log( P_{/RG}(H) )$



classes

original



Markovian labeling



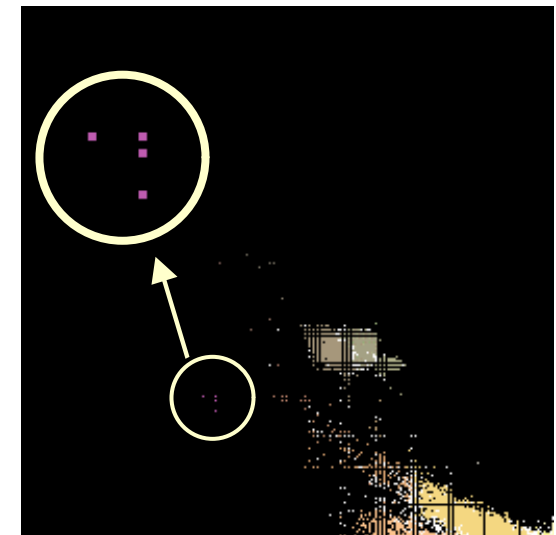
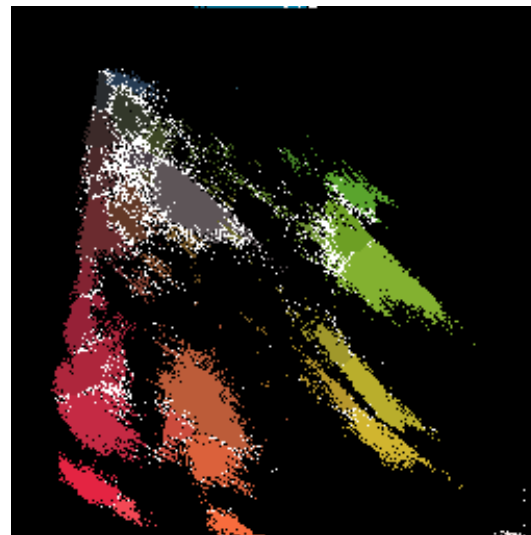
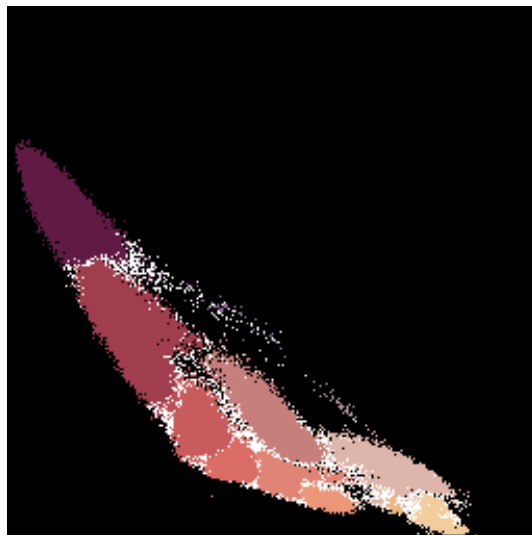
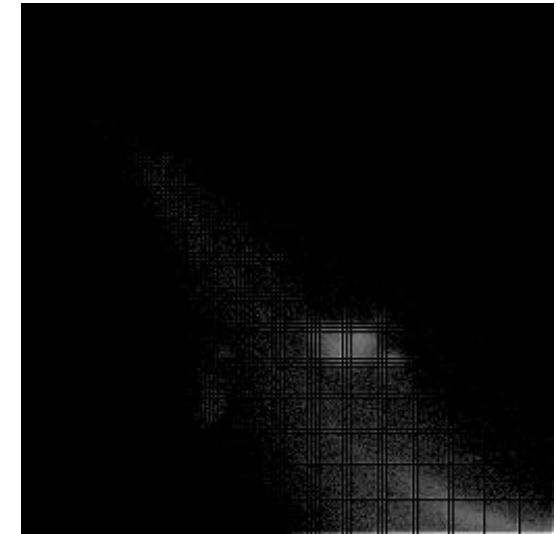
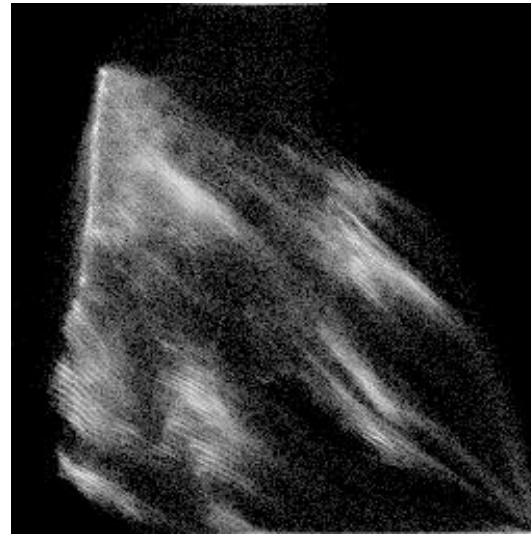
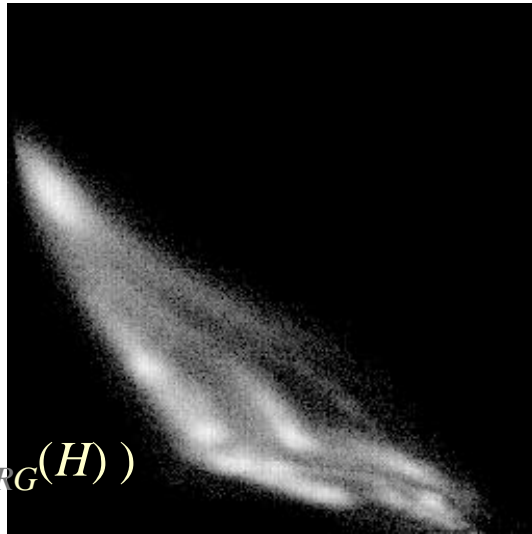
lena

jbeanc

tiffany

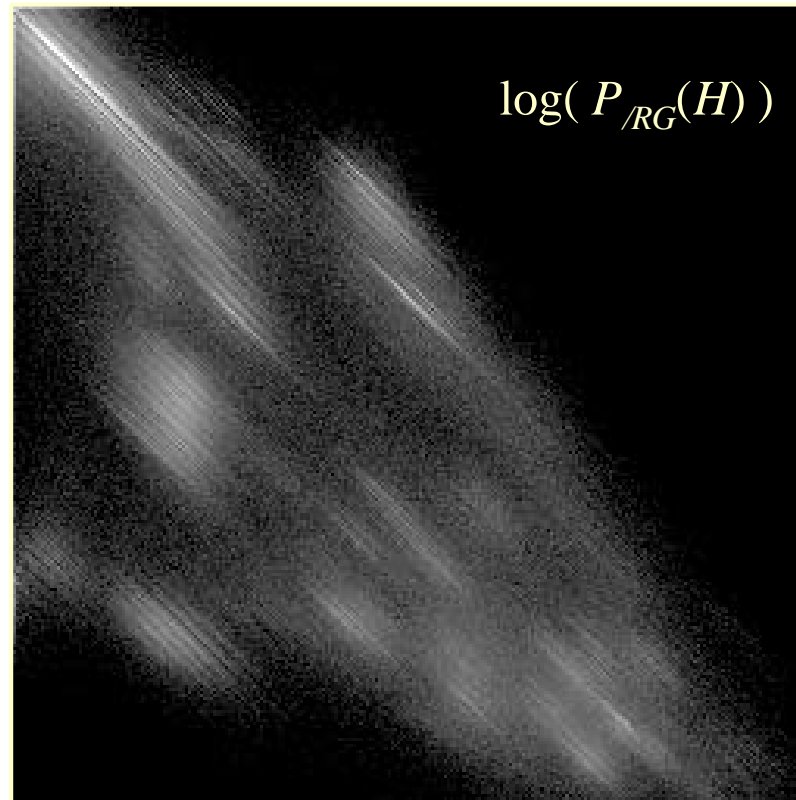
$\log( P_{/RG}(H) )$

clusters



# What about results from extreme data?

(oops... so many clusters! It should be a...)

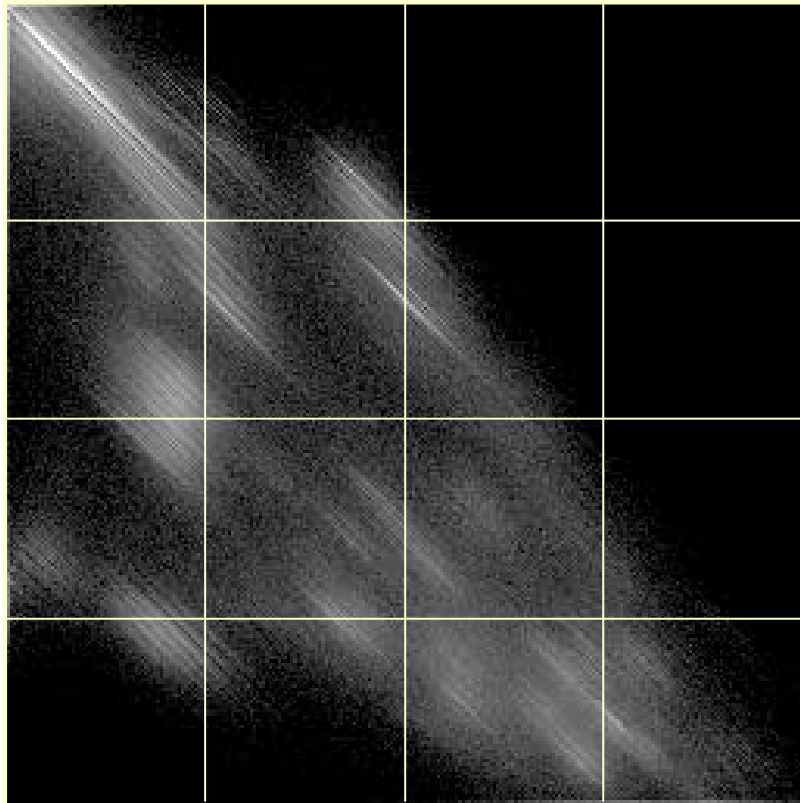




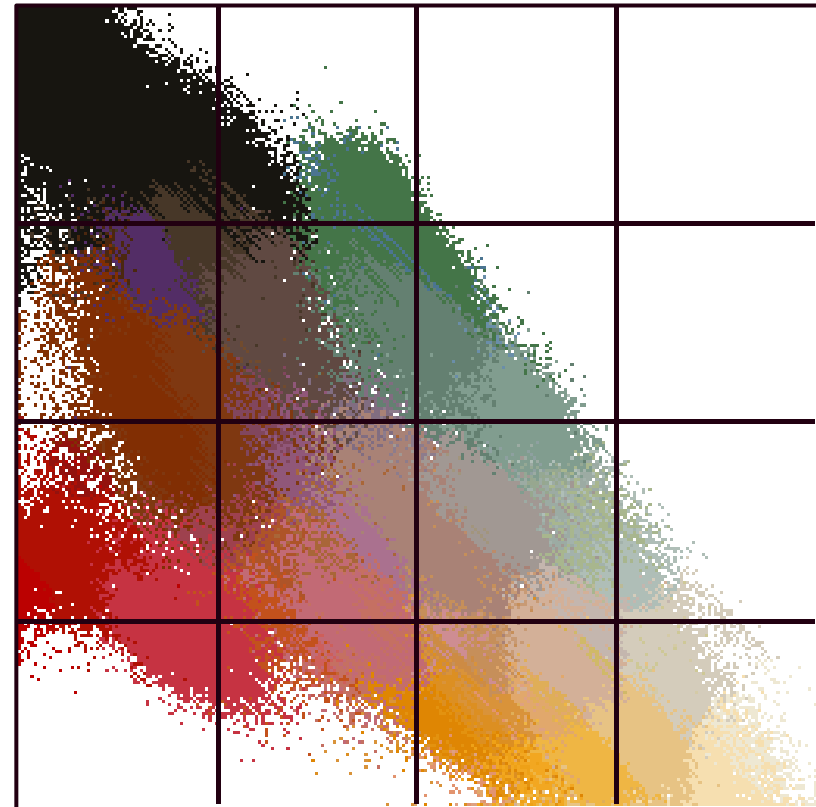
## ...Kandinsky



$\log( P_{/RG}(H) )$



classes





part of  
original  
image



non-  
contextual  
labeling



# Conclusion

- Original use of the connected watershed algorithm:
  - leads to an automatic classification method
  - is applied to color image segmentation
  - provides rather good and robust results

<http://www.lrde.epita.fr/download>

- *But:*
  - needs to be refined by merging (to improve the segmentation) and/or splitting classes (to serve as an halftoning method)
  - cannot separate two clusters when they closely mix
  - is memory consuming (3D feature space)