

New Algorithms for Multivalued Component Trees

Nicolas Passat¹, Romain Perrin², Jimmy Francky Randrianasoa^{2,3}, Camille Kurtz⁴, Benoît Naegel²

¹ Université de Reims Champagne Ardenne, CRESTIC, Reims, France

² Université de Strasbourg, CNRS, ICube, Strasbourg, France

³ EPITA Research Laboratory (LRE), Paris, France

⁴ Université Paris Cité, LIPADE, Paris, France



Motivation

The component tree (CT) [3] can model grey-level images for various image processing / analysis purposes (filtering, segmentation, registration, retrieval...). Its generalized version, the multivalued component tree (MCT) [1] can model images with hierarchically organized values. We provide new tools to handle MCTs:

- a new algorithm for the construction of MCTs;
- two strategies for building hierarchical orders on values, required to further build MCTs.

Multivalued Component Tree

Let $\Theta = (\Omega, \sim)$ be a non-directed graph. Let $\mathcal{C}[X]$ be the set of the connected components of $X \subseteq \Omega$. Let \mathbb{V} be a finite set and \leq a hierarchical order on \mathbb{V} , i.e. an order (1) which admits a minimum (resp. a maximum) and (2) such that for any $v \in \mathbb{V}$, the subset of the elements lower (resp. greater) than v is totally ordered by \leq .

Let us consider an image $\mathcal{F} : \Omega \rightarrow \mathbb{V}$. The threshold set of \mathcal{F} at value $v \in \mathbb{V}$ is defined by $\Lambda_v(\mathcal{F}) = \{\mathbf{x} \in \Omega \mid v \leq \mathcal{F}(\mathbf{x})\}$. We define the set of nodes of the MCT as

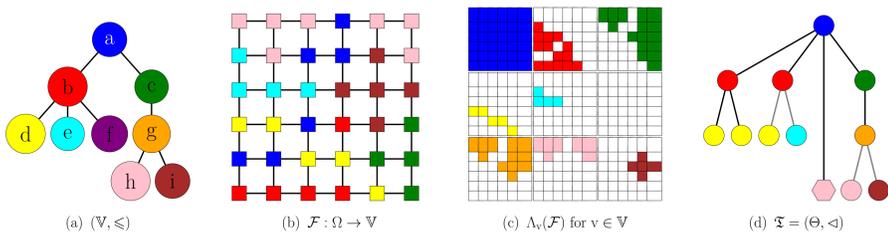
$$\Theta = \bigcup_{v \in \mathbb{V}} \mathcal{C}[\Lambda_v(\mathcal{F})] \quad (1)$$

with $\mathbb{I}(X) = \{v \in \mathbb{V} \mid X \in \mathcal{C}[\Lambda_v(\mathcal{F})]\}$, $\omega(X) = \bigvee^{\leq} \mathbb{I}(X)$ and $\tau(X) = |\mathbb{I}(X)|$ for any node $X \in \Theta$.

The inclusion relation \subseteq is a hierarchical order on Θ . Let \triangleleft be the reflexive-transitive reduction of \subseteq . The Hasse diagram $\mathfrak{T} = (\Theta, \triangleleft)$ of (Θ, \subseteq) is the multivalued component tree of the image \mathcal{F} . For any node $X \in \Theta$, we set $\rho(X) = X \setminus \bigcup_{Y \triangleleft X} Y = \{\mathbf{x} \in \Omega \mid \mathcal{F}(\mathbf{x}) = \omega(X)\}$.

The MCT \mathfrak{T} is an image model of the image \mathcal{F} :

$$\forall \mathbf{x} \in \Omega, \mathcal{F}(\mathbf{x}) = \bigvee_{X \in \Theta} \mathbf{1}_{(X, \omega(X))}(\mathbf{x}) \quad (2)$$



Building the Multivalued Component Tree

This construction algorithm derives from the CT construction of [3].

- **nodes**: stores the nodes of the multivalued component tree.
- **points**: stores the processed points of the image.
- **status**: stores the status of each point of the image.
- **nb_nodes** and **index**: store the number of nodes already fully built and the index of the node currently built at each value of \mathbb{V} .
- **progress**: indicates if there exists a node at value v , currently under construction or to be built, which is an ancestor of the node at value u currently being defined.

Algorithm 1: Build the multivalued component tree

Input: $(\Omega, \sim), (\mathbb{V}, \leq), \mathcal{F} : \Omega \rightarrow \mathbb{V}$

Output: $\mathfrak{T} = (\Theta, \triangleleft)$

Build **nodes**, **points**, **status**, **nb_nodes**, **index**, **progress**

$v_{\min} := \bigwedge^{\leq} \mathbb{V}$

Choose $\mathbf{x}_{\min} \in \Omega$ such that $\mathcal{F}(\mathbf{x}_{\min}) = v_{\min}$

points[v_{\min}].add(\mathbf{x}_{\min})

progress[v_{\min}] := true

Flood(v_{\min})

Function Flood

Input: $u \in \mathbb{V}$: current level

Output: $w \in \mathbb{V}$: value of the parent node of the root of the built (partial) MCT at value u

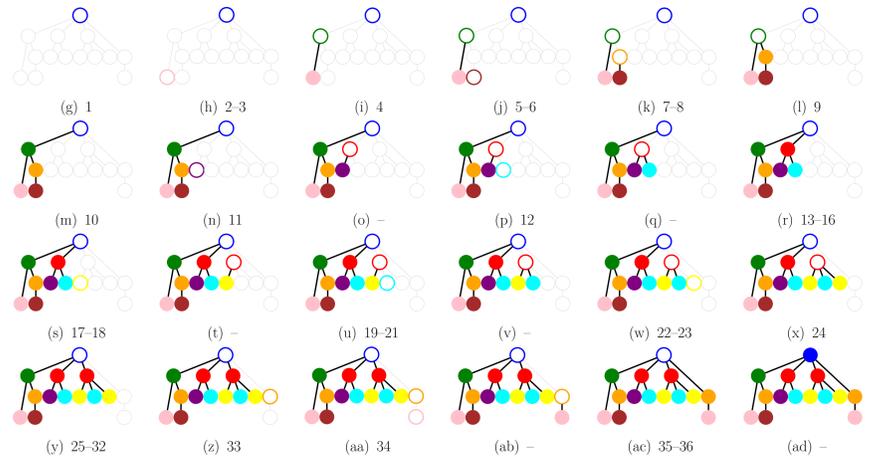
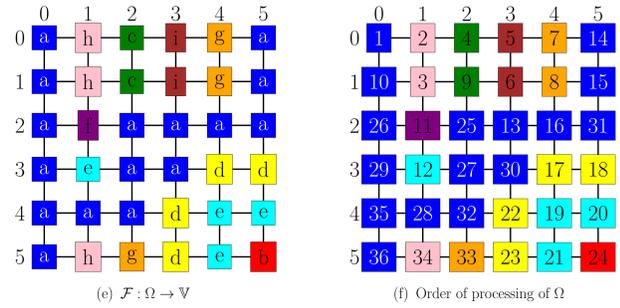
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while !(points[u].empty()) do
  x := points[u].remove()
  if index[u] > nb_nodes[u] then
    nb_nodes[u] := index[u]
    X := create_node() // new node in Theta
    nodes[u].insert(X)
  if F(x) != u then
    w := F(x)
    points[w].add(x)
    progress[w] := true
    while u < w do w := Flood(w)
  else
    status[x] := index[u]
    nodes[u][index[u]].add_to_proper_part(x)
    foreach y ~ x do
      w := F(y)
      if status[y] == -1 then
        if u <= w then w_hat := w
        else w_hat := bigwedge^{<=}{u, w}
        points[w_hat].add(y)
        status[y] := 0
        progress[w_hat] := true
        while u < w_hat do w_hat := Flood(w_hat)
  if u == v_min then
    w := epsilon
  else
    w := bigwedge^{<=}{w' in V | w' < u}
    while progress[w] == false do w := bigwedge^{<=}{w' in V | w' < w}
    create_edge(nodes[u][index[u]], nodes[w][index[w]]) // new edge in <
  progress[u] := false
  index[u] ++

```

Running the Construction Algorithm

Construction of the MCT of an image $\mathcal{F} : \Omega \rightarrow \mathbb{V}$. At a current stage: a plain coloured node is fully built; a contour-coloured node is under construction; a non-coloured node has not been considered yet; a black edge is built; a light gray edge is not built.



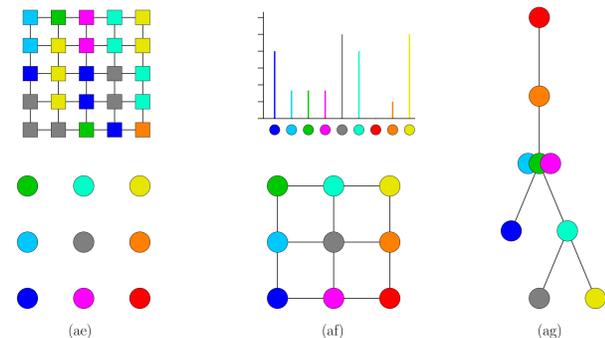
Hierarchical order construction (1/2): (Pre)ordering the value set

Building the MCT requires a hierarchical order on \mathbb{V} .

First, we can build a hierarchical preorder $\leq_{\mathbb{V}}$ on \mathbb{V} . This can be done by building the CT of an "image" composed by the value set. It is only required that \mathbb{V} be endowed with:

- an adjacency $\sim_{\mathbb{V}}$, allowing to map a graph structure on \mathbb{V} ;
- a function $\delta_{\mathbb{V}} : \mathbb{V} \rightarrow \mathbb{N}$, allowing to associate to each element of \mathbb{V} a value within the totally ordered set (\mathbb{N}, \leq) .

The CT of $\delta_{\mathbb{V}}$ is a hierarchical preorder $\leq_{\mathbb{V}}$ on \mathbb{V} .

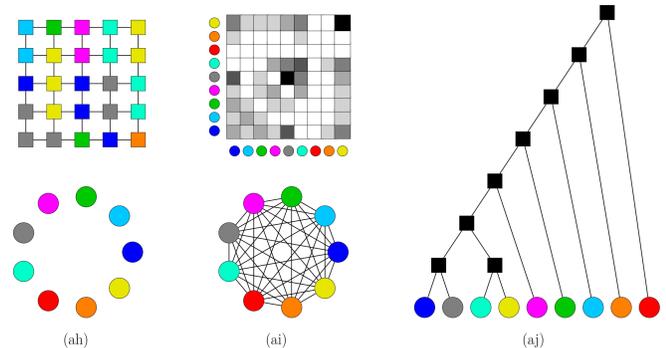


Hierarchical order construction (2/2): Ordering the enriched value set

Second, we can build hierarchical order $\leq_{\mathbb{W}}$ on $\mathbb{W} \supset \mathbb{V}$ so that the elements of \mathbb{V} are the maximal elements with respect to $\leq_{\mathbb{W}}$.

This can be done by building the binary partition tree (BPT) [2] of an "image" composed by the value set $\leq_{\mathbb{V}}$. It is only required that \mathbb{V} be endowed with:

- an adjacency $\sim_{\mathbb{V}}$, allowing to map a graph structure on \mathbb{V} ;
- a priority function $\delta_{\sim_{\mathbb{V}}} : \sim_{\mathbb{V}} \rightarrow \mathbb{N}$, allowing to determine the couples of nodes to be merged in priority.



References

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