# Segmentation of Curvilinear Objects using a Watershed-Based Curve Adjacency Graph



#### Thierry Géraud

**EPITA** Research and Development Laboratory 14-16 rue Voltaire, F-94276 Le Kremlin-Bicêtre, France A classical segmentation framework

Compute gradient norm image

objects' contours are crest lines

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Apply a morphological closing when *no prior* info are known about objects; small local minima are removed

Run the watershed transform (WST)

an over-segmentation is obtained

Extract the region-adjacency graph (RAG)

the image is described by a structure

Perform region merging as a Markov random field (MRF) labeling final segmentation results from a global optimization process

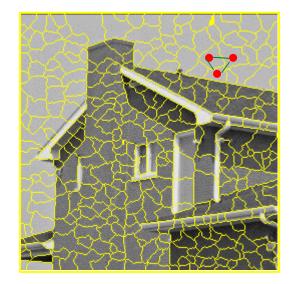
# A classical segmentation framework 2/3 GMI closed Original gradient norm image (GMI)

Morphological closing ensures that regions have a sufficient size to get relevant statistical features

# A classical segmentation framework

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RAG defined upon WST's result => input of a Markovian relaxation



"WST+RAG+MRF" framework:

- a region-oriented approach
- efficient
- adaptable
- general
- leads to effective results (global optimization)
- reliable

What about curvilinear objects?

- In the "WST+**R**AG+MRF" framework:
  - objects to be segmented are **regions**
  - GMI is a "potential" image that highlights contours

contours are curvilinear objects!

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- morphological closing is used to simplify data
- contours are included in the watershed line

#### the WST is a curvilinear object extractor!

- a RAG is defined to get structured data
- MRF on RAG is a powerful tool to process an over-segmentation

#### so we propose to adapt the "WST+RAG+MRF" framework to the segmentation of curvilinear objects...

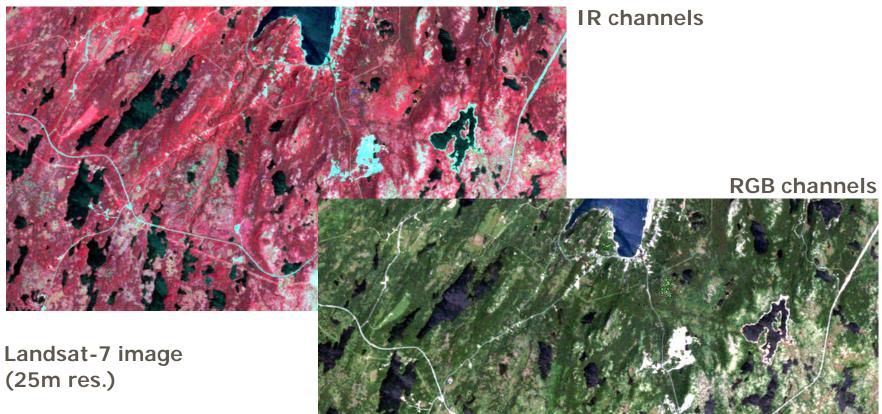
## What about curvilinear objects?

- In the "WST+CAG+MRF" framework:
  - objects to be segmented are curvilinear
  - we need a "potential" image that highlights objects
  - morphological closing can also be used to simplify data
  - curvilinear objects are included in the watershed line
  - a curve adjacency graph (CAG) is defined to get structured data

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MRF on CAG is a powerful tool to process an over-segmentation

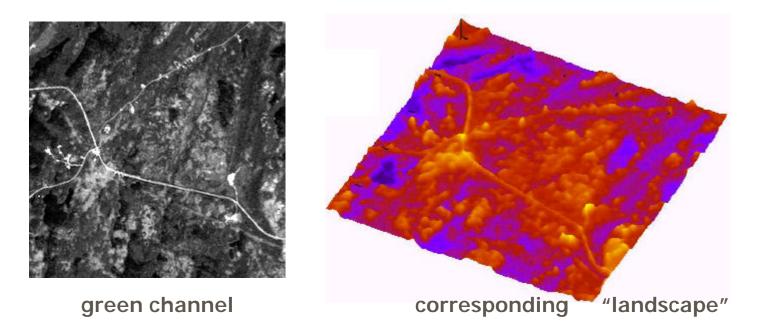
## Case study -- original image



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# Case study -- potential image

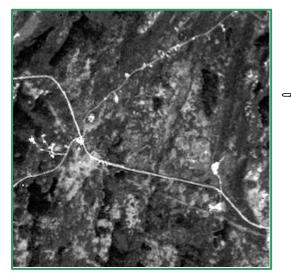
#### potential image crest lines should include objects to be segmented



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# Case study -- WST (without closing first)

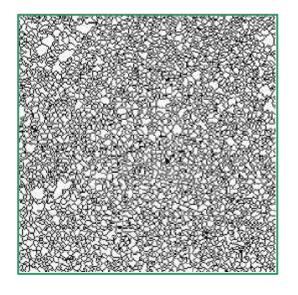
#### Potential image



### 💿 one local minimum

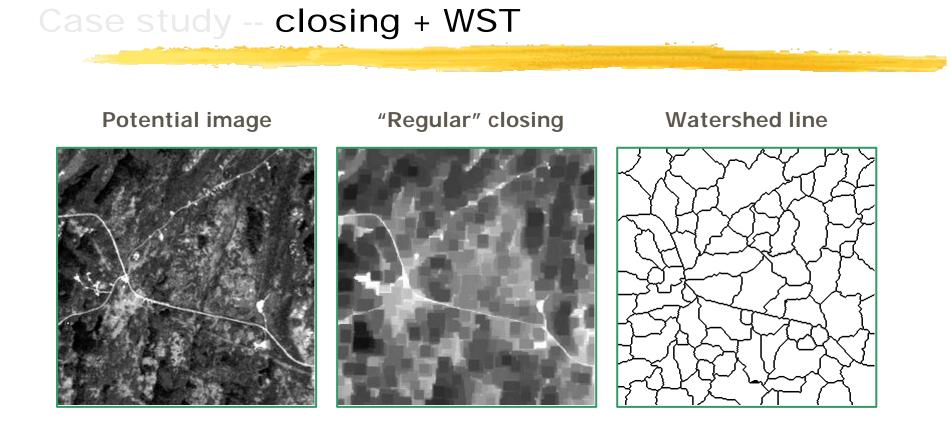
gives one region  $\ensuremath{\textcircled{\sc s}}$ 

#### Watershed line



#### object to be segmented is somewhere (but where?) 🙁

too many elementary pieces of watershed line actually too many local minima in the potential image



with the "regular" morphological closing, crest lines are shifted whatever the shape of the structural element this artifact increases along with the size of the struct.elt.

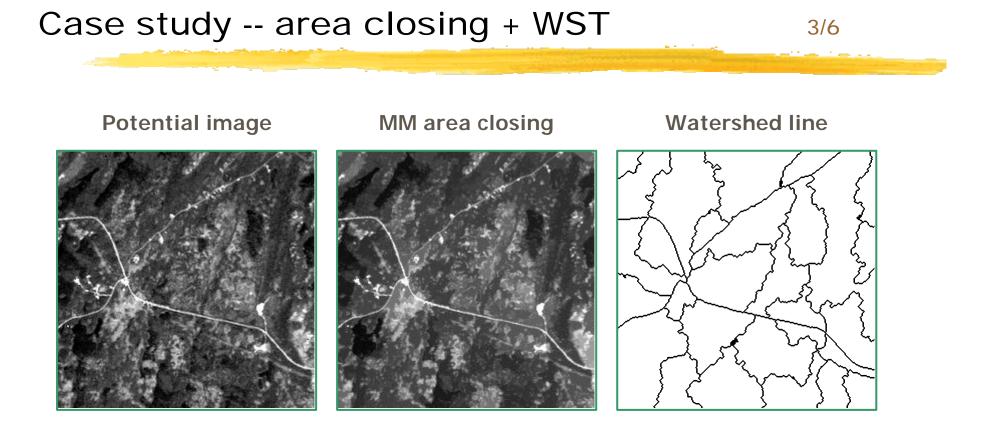
# Case study -- attribute closing

*B* is a binary image, *p* is a pixel of *B*   $B_i$  is a connected component of *B*   $B_{i(p)}$  is the connected component of *B* containing *p a* is an attribute of a connected component (e.g., its area)  $\lambda$  is a positive value

binary attribute opening:  $g_{l}^{a}(B) = \{ p \mid a(B_{i(p)}) > \lambda \}$ or:  $g_{l}^{a}(B) = \bigcup \{ B_{i} \mid a(B_{i}) > \lambda \}$ 

binary attribute closing:  $y_l^a(B) = inv(g_l^a(inv(B)))$ 

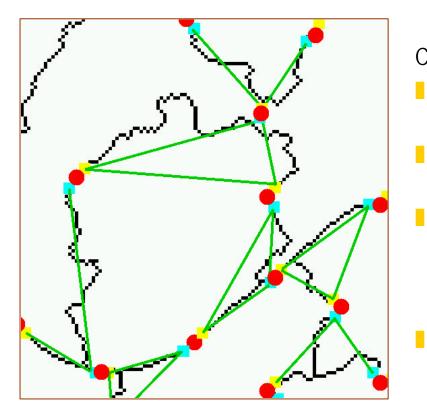
*I* is a gray-level image gray-level attribute opening:  $g_{I}^{a}(I) = \text{merge}_{I}(g_{I}^{a}(\text{split}_{I}(I)))$ 



area closing removes local minima without shifting crest lines

threshold value  $\lambda$  ensures a minimal region area O(N log N) complexity [Meijster and Wilkinson, 1999]

## Case study -- Curve adjacency graph



CAG:

node = piece of watershed line
 separating two basins (shed)

edge = connection between two sheds

node attributes: length, mean curvature, mean curvature deviation, mean potential, surrounding contrast, etc.

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edge attributes: spatial continuity, etc.

## Case study -- Markov random fields

- *X* is the solution MRF; a shed *s* should be assigned a Boolean label:
  - $x_s =$ true | false (meaning object or not)
- *Y* is the observation MRF:

 $y_s$  encloses attributes of CAG shed s

Hypothesis:

$$P(Y = y | X = x) = \prod_{s} P(Y_{s} = y_{s} | X_{s} = x_{s})$$

$$P(X = x) = \prod_{s} P(X_{s} = x_{s} | X_{N(s)} = x_{N(s)})$$

Bayesian solution (e.g., given by the Metropolis algorithm): arg max<sub>x</sub>  $P(X = x / Y = y) = \arg \min_x (U_d(y_s, x_s) + U_c(x_s, x_{N(s)}))$ data term contextual term Case study -- energy terms in MRF

Both energy terms depend on your problem...

Data term:

geometry of a piece of object

its environment in input image

Contextual term:

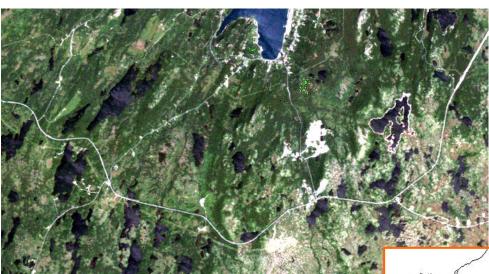
global object geometry

for instance:

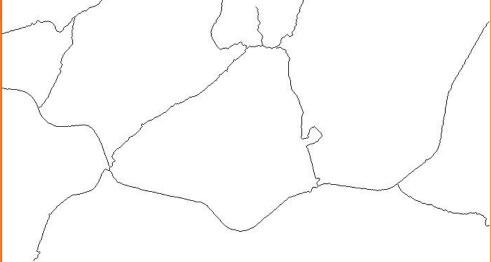
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o <u>'oo'</u> @ <mark>'o</mark> o_o	High	0
	Medium	0.2
	Low	1
	Low	1

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# Case study -- results

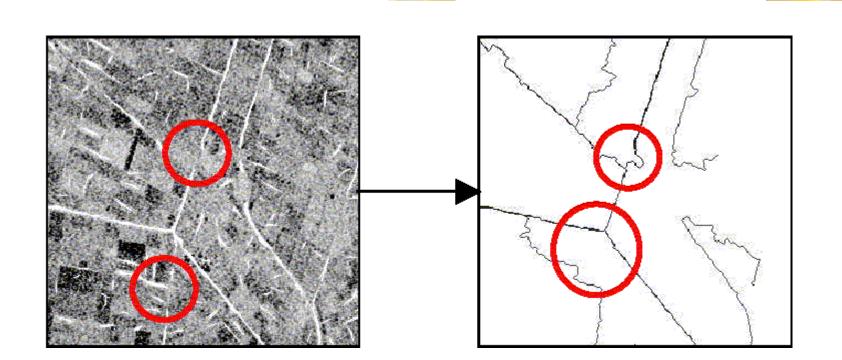


original image: 2.10<sup>6</sup> pixels 1,7GHz PC running GNU/Linux processing time: **20 s** 



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## Drawback



watershed line cannot invent some data

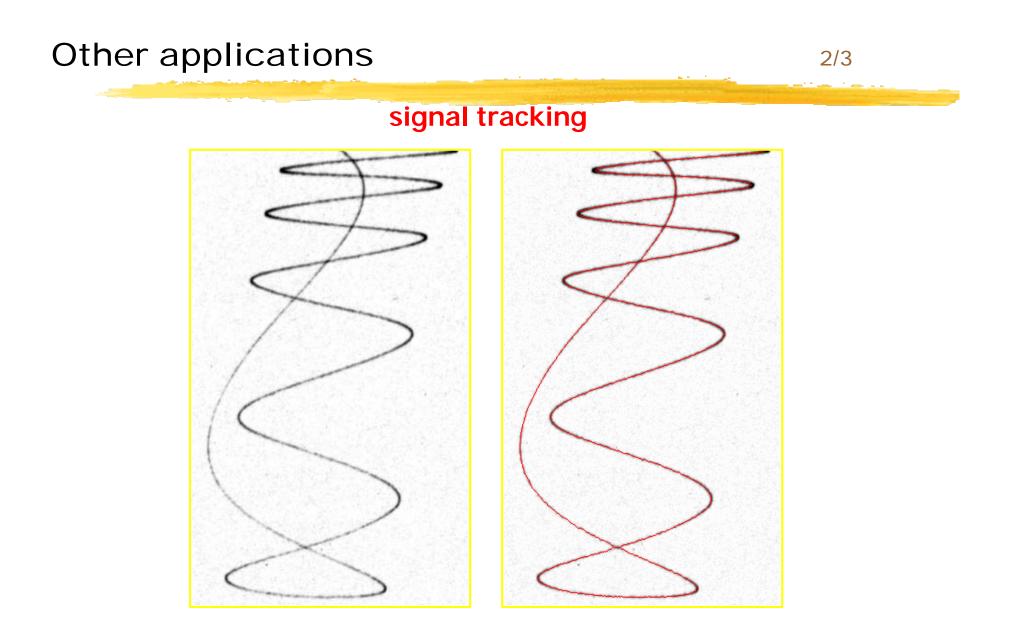
=> some bad connections or disconnections can appear

# Other applications

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### form segmentation

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# Other applications

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## region segmentation (!)



## Conclusion

An efficient framework to segment curvilinear objects

Highly adaptable through:

- potential image definition
- Markov random fields parameterization

## Perspectives:

- numerous applications
- multi-scale approach (thanks to attribute closing properties)

Extra information

Source code available from http://www.lrde.epita.fr

Developed using Olena:

- our generic image processing library
- free software under the GNU Public Licence (GPL)

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thanks for your attention; any question?