mbeddr How we built it and what we have learned

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mbeddr



An extensible set of integrated languages for embedded software engineering.

User Extensions	to be defined by users										
Default Extensions	Test Support	Decision Tables	Logging & Tracing								
	Compo- nents	Physical Units	State Machines	State Machine Verification	Decision Tables	Component Contracts			Glossaries	Use Cases & Scenarios	
Core		C99		Model Checking	SMT Solving	Dataflow Analysis	Visual- ization	PLE Variability	Documen- tation	Requirements & Tracing	Reports & Assessments
Platform	JetBrains MPS										
Backend Tool	C Compiler, Debugger and Importer		NuSMV	Yices	СВМС	PlantUN	/IL LaTe	(
	Implementation Concern			Analysis Concern			Process Concern				

99 Specific Languages

mbeddr

```
StateMachines - tutorial - [~/Documents/mbeddr/mbeddr.core/code/applications/tutorial]
□ 🖺 🧭 🥓 🤌 🐰 🗻 🗂 🗘 🖨 🕽 MbeddrTutorial 🔻 🕨 💥
StateMachines
                                                                           StateMachines
     #constant TAKEOFF = 100; -> implements PointsForTakeoff
                                                                                #constant TAKEOFF = 100; -> implements PointsForTakeoff
     #constant HIGH SPEED = 10; -> implements FasterThan100
                                                                                #constant HIGH SPEED = 10; -> implements FasterThan100
                                                                                #constant VERY HIGH SPEED = 20; -> implements FasterThan200
     #constant VERY HIGH SPEED = 20; -> implements FasterThan200
     #constant LANDING = 100; -> implements FullStop
                                                                                #constant LANDING = 100; -> implements FullStop
    [verifiable]
                                                                               [verifiable]
    exported statemachine FlightAnalyzer initial = beforeFlight {
                                                                               exported statemachine FlightAnalyzer initial = beforeFlight
      in event next(Trackpoint* tp) <no binding>
                                                                                               next(Trackpoint* tp)
                                                                                  beforeFlight // Here is a comment on a transition.
      in event reset() <no binding>
                                                                                               [tp->alt == 0 m] -> airborne
      out event crashNotification() => raiseAlarm
      readable var int16 points = 0
                                                                                  airborne
                                                                                               [tp->alt == 0 m && tp->speed == 0] -> crashe
                                                                                               [tp->alt == 0 m && tp->speed > 0 mps] -> lan
      state beforeFlight {
        // Here is a comment on a transition.
                                                                                                [tp->speed > 200 mps && tp->alt == 0 m] ->
        on next [tp->alt == 0 m] -> airborne
                                                                                                [tp->speed > 100 mps && tp->speed <= 200 mp
         exit { points += TAKEOFF; } -> implements PointsForTakeoff
                                                                                                     tp->alt == 0 m] -> airborne
      } state bef Error: type int16/[m / s] is not comparable with (uint8 || int8)
                                                                                               [tp->speed == 0 mps] -> landed
                                                                                  landing
                                                                                                [tp->speed > 0 mps] -> landing -> implements Sho
      state airborne {
        on next [tp->alt == 0 m && tp->speed == 0] -> crashed
                                                                                  landed
                                                                                   ^DataStructures.Trackpoint.alt (Member)
        on next [tp->alt == 0 m && tp-> n alt
         on next [tp->speed > 200 mps & crashNotification ^StateMachines.FlightAnalyzer.crashNotification (OutEvent)
         on next [tp->speed > 100 mps & id
                                                                                    ^DataStructures.Trackpoint.id (Member)
                                          speed
                                                                                 ^DataStructures.Trackpoint.speed (Member)
        on reset [ ] -> beforeFlight
                                         m time
                                                                                  ^DataStructures.Trackpoint.time (Member)
      } state airborne
                                                                                     ^DataStructures.Trackpoint.x (Member)||lyzer initial = t
                                         n X
      state landing {
                                                                                     ^DataStructures.Trackpoint.y (Member)
                                                                                                                                next(Trackpoi
        on next [tp->speed == 0 mps] -> landed
                                                                                  beforeFlight
                                                                                                                                [tp->alt > 0
         on next [tp->speed > 0 mps] -> landing { points--; } -> imp
                                                                                  composite state airborne initial = flying { [onTheGround
```



itemis fortiss



Open Source @ eclipse.org Eclipse Public License 1.0 http://mbeddr.com





itemis France: Smart Meter

First significant mbeddr project
ca. 100,000 LoC
about to be finished
great modularity due to components
uses physical units extensively
great test coverage due to special extensions

Embeddr

ACCEnT Control.Lab

LMS INTERNATIONAL

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LMS is a leading provider of test and mechatronic simulation software and engineering services in the automotive, aerospace and other advanced manufacturing industries. As a business segment within Siemens PLM Software, LMS provides a unique portfolio of products and services for manufacturing companies to manage the complexities of tomorrow's product development by incorporating model-based mechatronic simulation and advanced testing in the product development process. LMS tunes into mission-critical engineering attributes, ranging from system dynamics, structural integrity and sound quality to durability, safety and power consumption. With multi-domain and mechatronic simulation solutions, LMS addresses the complex engineering challenges associated with intelligent system design and model-based systems engineering. Thanks to its technology and more than 1250 dedicated people, LMS has become the partner of choice of more than 5000 manufacturing companies worldwide. LMS operates in more than 30 key locations around the world.



Siemens PLM Software





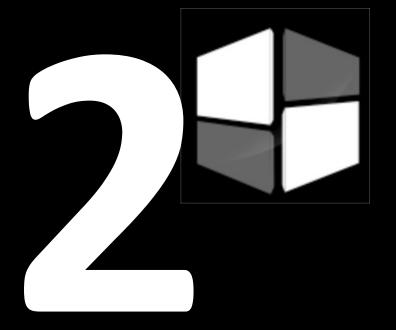
A Siemens Business



20+ Projects in various stages by various "Big Name" companies.

Approach also used in other Domains

Insurance, Finance

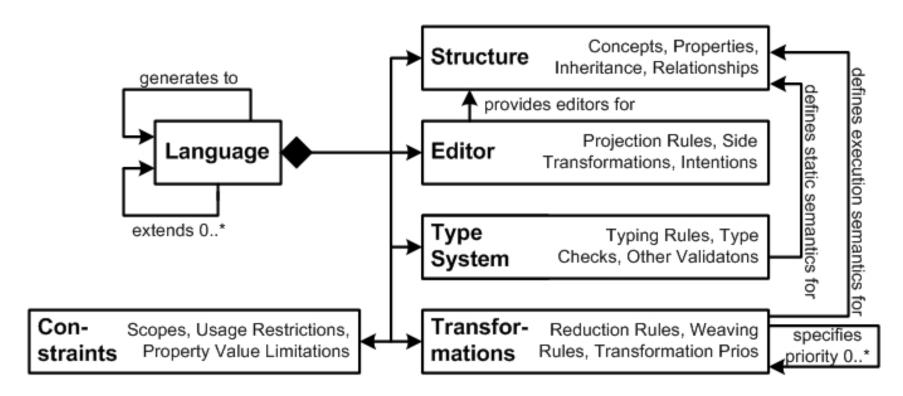


The Language Workbench



Open Source
Apache 2.0
http://jetbrains.com/mps

[Language Workbench]



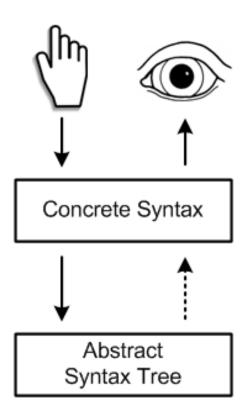
+ Refactorings, Find Usages, Syntax Coloring, Debugging, ...



Projectional Editing

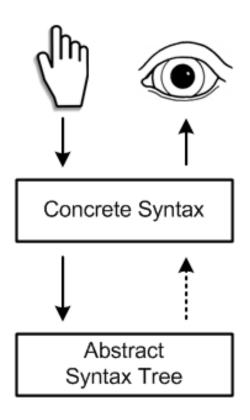
[Projectional Editing]

Parsing

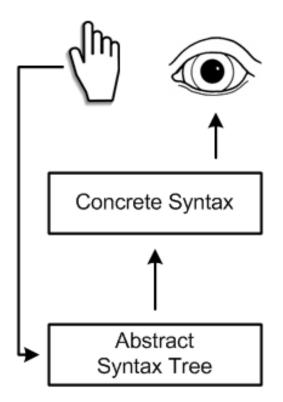


[Projectional Editing]

Parsing



Projectional Editing

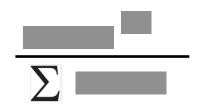


[Projectional Editing] Syntactic Flexibility

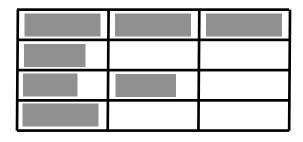
Regular Code/Text



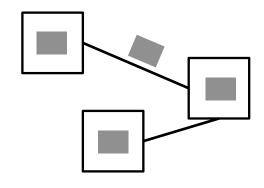
Mathematical



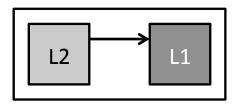
Tables



Graphical



[Projectional Editing] Language Composition



Separate Files

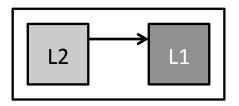
Type System
Transformation
Constraints



In One File

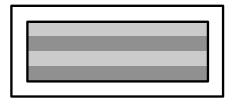
Type System
Transformation
Constraints
Syntax
IDE

[Projectional Editing] Language Composition



Separate Files

Type System
Transformation
Constraints

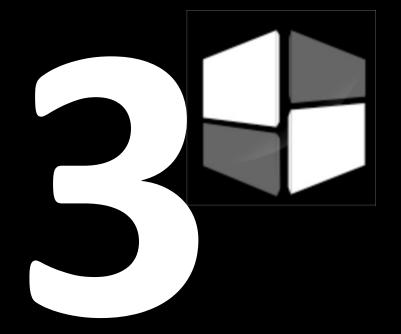


In One File

Type System
Transformation
Constraints
Syntax
IDE



50+ extensions to C 10+ extensions to requirements lang.



Bottom Line Up-Front



Resarch Project Completed

Resarch Project Completed Lively OS project

Resarch Project Completed Lively OS project Paying customers

Resarch Project Completed Lively OS project Paying customers Expanded to other domains

Resarch Project Completed Lively OS project Paying customers Expanded to other domains Learned a lot

Resarch Project Completed Lively OS project Paying customers Expanded to other domains Learned a lot

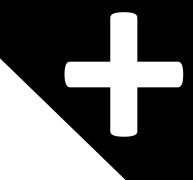
Resarch Project Completed Lively OS project **Paying customers Expanded to other domains** Learned a lot Papers + my PhD

Resarch Project Completed Lively OS project Paying customers Expanded to other domains Learned a lot Papers + my PhD **New Research Opportunities**

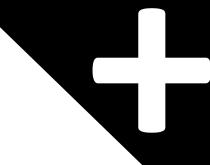


But there were Problems/Challenges/Lessons Learned

Good Experience.



Good Experience.

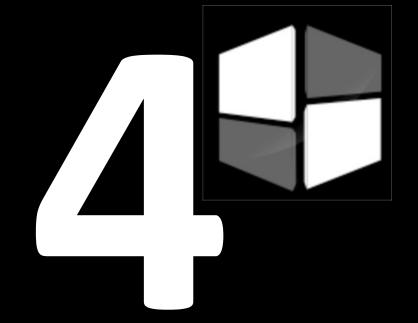


Neutral Observation

Good Experience.

Neutral Observation

Problem/Challenge



Lessons: mbeddr-related

Default extensions are useful, in particular components, state machines and units.

Easy and useful to add customer specific extensions.

The non-code languages (Req, PLE, Doc) are more useful and important than we initially thought.

RCP version of MPS crucial for end users.
We had underestimated this.

Decided not to make extensions BL independent, they are actually C extensions and cannot be used with other base languages.

mbeddr requires a fundamental change in how people develop software. Makes it hard to "sell". Integration with analysis tools work and is useful, but performance and config of the analysis is still an issue. (leaky abstraction)

Do more verification on code level than on model level because of consistency problem with code.

Writing optimizing generators is hard.

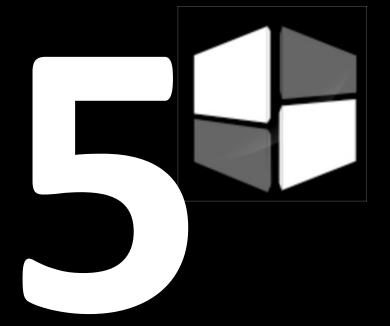
Underestimated importance of style of generated code.

Some extensions had to be redone (units) because we didn't get them right the first time.

Splitting C into several languages not so useful – dependencies!

Some of our "C cleanups" were not sustainable.

Importer more challenging than expected (because of #preprocessor)



Lessons: MPS-related

Modularity works in principle and practice

MPS' approach scales to non-trivial and many languages.

Flexible notations actually work and are useful in practice.

Decoupling Notation from Language works.

MPS is easily extensible with new notational styles.

Editor Usability less and less of a Problem as MPS evolved/s.

VCS integration works well (diff/merge)

MPS can be extended with the same means – bootstrapped.

Language Testing works well enough to stabilize non-trivial languages (and type systems).

MPS also supports debugging of DSLs even though we had to extend the mechanism

MPS had quite a number of bugs and a few conceptual problems. We worked with JetBrains to resolve them.

Type system is the most challenging aspect of language definition.

No direct support for detecting semantic interations between languages

Modularity: Sometimes base language requires change (introduction of abstract class or interface)

Model Migration upon language change is sometimes tedious. To be fixed in 3.2

Renaming languages is sometimes painful (because of bugs)

Cross-model
generation not
possible – being
worked on right now.

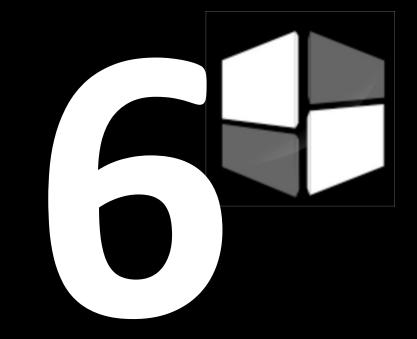
Ability to create additional language aspects missing (you can existing ones)

Debugger definition separate from generator; leads to duplication

Tracing back from the generated code to the model is not always consistent; problems for debugger and analysis.

many aspects of language definition too "procedural" and hence hard to analyze.

Due to the open world assumption of MPS, there is a "feeling of incompleteness" in aspects like e.g. in lifting analyses results.



Lessons:

Life in General

A govenment project that really worked together on **one** tool – rare!

mbeddr was only possible because of a highly motivated small team.



mbeddr was only possible because of **itemis** support.

mbeddr was only possible because of **ERAINS** support.

Underestimated "overhead": installer, docs, ...

Not enough time for refactorings - as usual.

More and more team leading and organization for me and Bernd.

The best 3 years in my professional life so far.



Thank you!

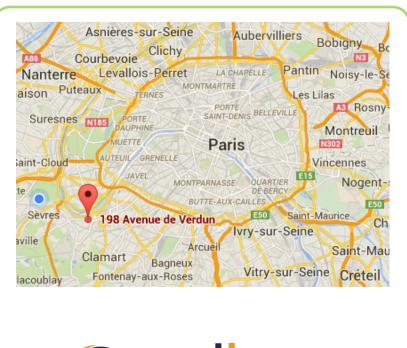


itemis France

- Company profile
- Founded in 2008
- Based in Issy-les-Moulineaux
- 7 employees
- Jeune Entreprise Innovante

Focus

- Model-driven tools
- Embedded systems







Internship ("stage"): Smart Metering

Context

- 3-phase smart meter for Saudi Arabian market
- Measurement of electrical energy consumption, data analysis, automatic meter reading
- Fully developed by itemis France (hardware, software, casing)

Internship task

- Development of advanced smart metering functions (multi-tariff support, consumption profiles, etc.)
- Integration on embedded target (Texas Instruments MSP430)
- Using mbeddr and C



itemis



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