

Regular Model Checking of Epistemic Logic

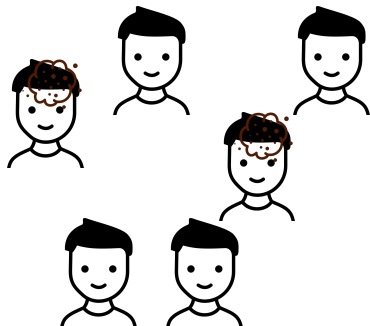
Daniel Stan¹

June 27, 2022

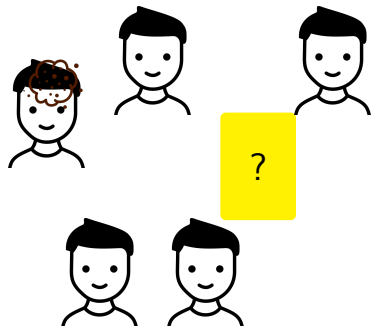


joint work with Anthony W. Lin^{1,2}, Felix Thoma¹

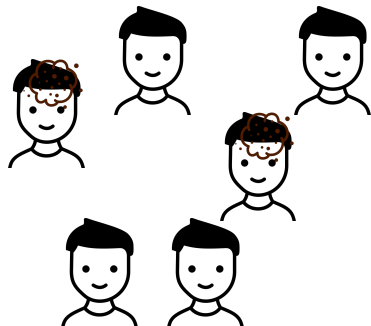
Muddy Children Puzzle (Littlewood, 1953)




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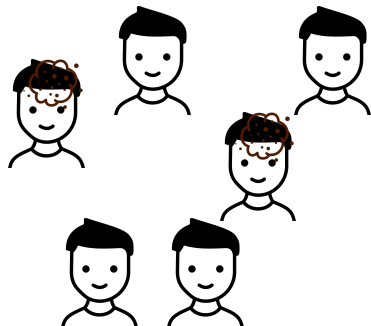



Muddy Children Puzzle (Littlewood, 1953)



 **Father:** at least one of you is muddy!

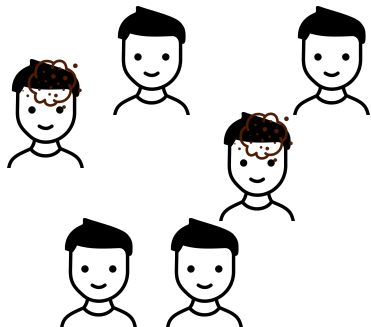
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 **Father:** at least one of you is muddy!


Children: ???

Muddy Children Puzzle (Littlewood, 1953)

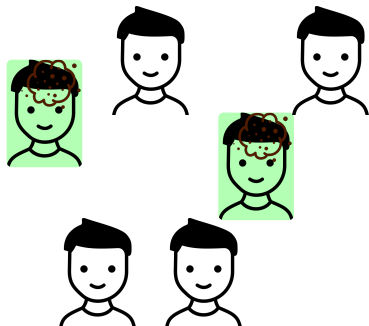



 **Father:** at least one of you is muddy!

Children: ???


 **Father:** indeed, no one knows.


Muddy Children Puzzle (Littlewood, 1953)



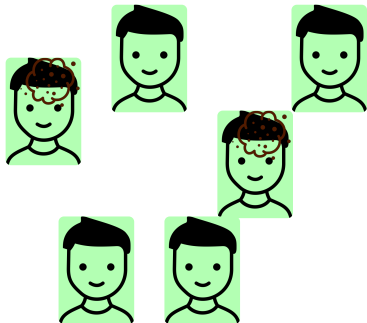
 **Father:** at least one of you is muddy!


Children: ???

 **Father:** indeed, no one knows.


 **Muddy children:** ah, yes we know we're muddy.


Muddy Children Puzzle (Littlewood, 1953)




 **Father:** at least one of you is muddy!


Children: ???

 **Father:** indeed, no one knows.


 **Muddy children:** ah, yes we know we're muddy.

 **Clean children:** ah, yes we know we're clean.

Setting


- ▶ **Common Knowledge** framework
- ▶ Communication primitive: **Public Announcement** 
- ▶ **Model checking** problem: given some model \mathcal{M} and some specification φ , decide whether $\mathcal{M} \models \varphi$;
- ▶ **Parameterized** problem: the number of agents (children) is **not fixed**.

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Applications: analysis of communication protocols involving identical arbitrarily many processes

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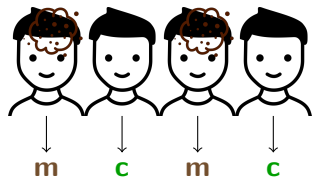
Applications: analysis of communication protocols involving identical arbitrarily many processes

Outline

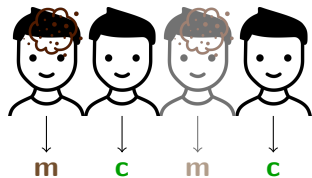
1. **Parameterized Public Announcement Logic on Regular Structures;**
2. **Active Learning of Iterated Public Announcement**
3. **Extensions**

1: Parameterized Public Announcement Logic (Modal Logic)

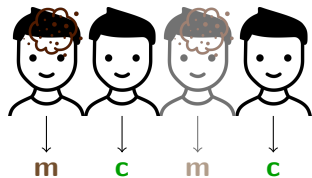
Indistinguishability Relation



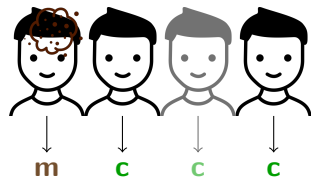
Indistinguishability Relation



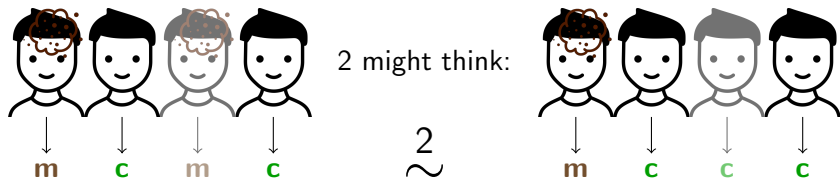
Indistinguishability Relation



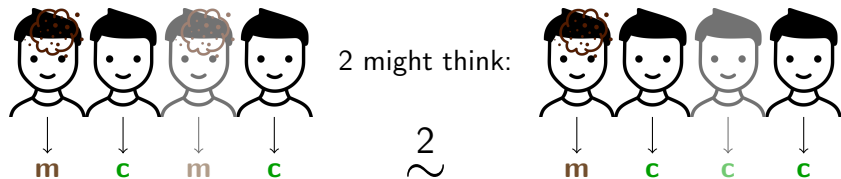
2 might think:



Indistinguishability Relation



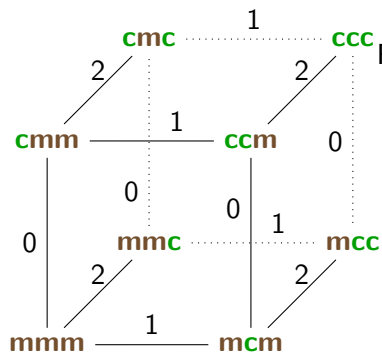
Indistinguishability Relation



(S5): For every i , \sim^i is an equivalence relation.

Kripke Structures

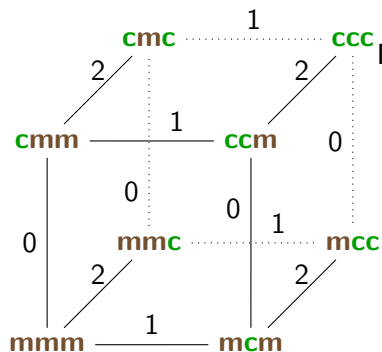
Case with 3 children



From a given state s ,

Kripke Structures

Case with 3 children

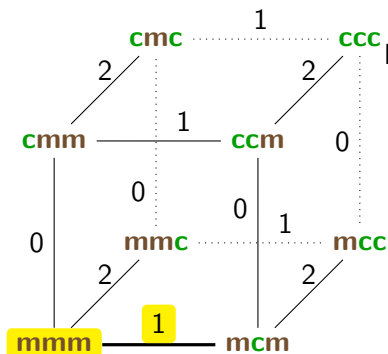


From a given state s ,

- ▶ If $s \stackrel{i}{\sim} t$, i may think we are in t .

Kripke Structures

Case with 3 children



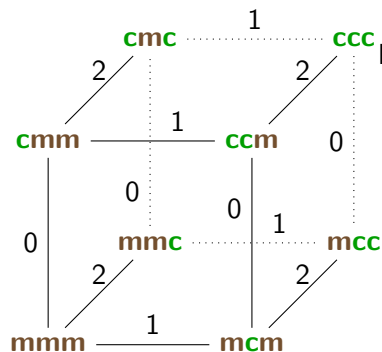
From **mmm**, agent 1 knows that third letter is **m**

From a given state s ,

- ▶ If $s \stackrel{i}{\sim} t$, i may think we are in t .
- ▶ If for all t such that $s \stackrel{i}{\sim} t$, t satisfies some property φ , then i knows that φ holds (from s).

Kripke Structures

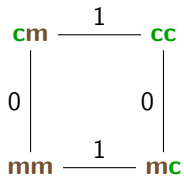
Case with 3 children



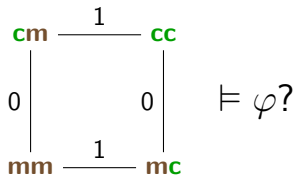
From a given state s ,

- ▶ If $s \stackrel{i}{\sim} t$, i may think we are in t .
- ▶ If for all t such that $s \stackrel{i}{\sim} t$, t satisfies some property φ , then i knows that φ holds (from s).
- ▶ Any agent knows the structure of the graph: *common knowledge*.

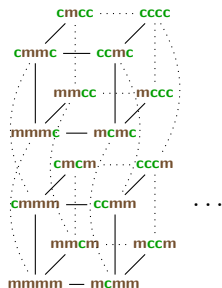
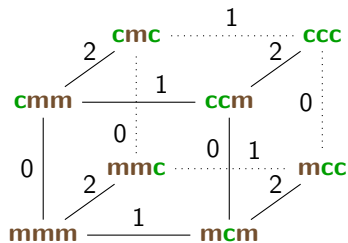
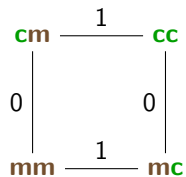
Parameterized Verification of a property φ



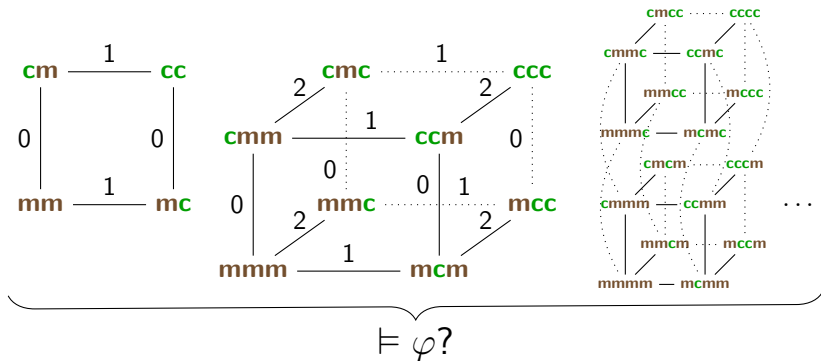
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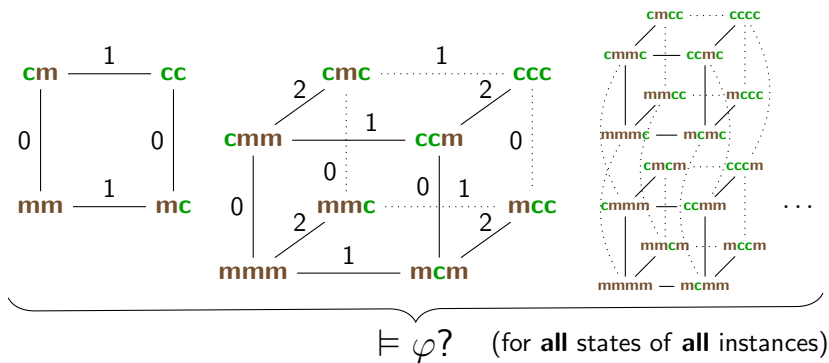


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\Leftrightarrow **Infinite** collection of systems

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PAL: Public Announcement Logic (Plaza, 07)

$$\varphi ::= p \mid \top \mid \varphi \wedge \varphi \mid \neg \varphi \mid K_a \varphi \mid \langle \varphi! \rangle \psi$$

Where:

$p \in AP$ is an atomic proposition;

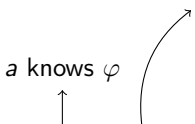
$a \in \mathbb{N}$ is a constant;

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After announcing φ , ψ holds

a knows φ

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$\varphi ::= p_i \mid \top \mid \varphi \wedge \psi \mid \neg \varphi \mid K_i \varphi \mid \langle \varphi! \rangle \psi \mid \exists i : \varphi \mid i = 0 \mid i \% k = 0 \mid i = j + a$

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i, j are index variables, for **agents** and **atomic propositions**.

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Where:

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i, j are index variables, for **agents** and **atomic propositions**. Modal logic, also similar to wS1S. Now combined with Public Announcements.

Semantics of a PPAL formula φ

$$\llbracket \varphi \rrbracket = \left(\begin{array}{ccc} & \text{cmc} & \text{ccc} \\ & \cdots 1 \cdots & \\ \text{cmm} & \xrightarrow{2} & \text{ccm} \\ & \vdots & \vdots \\ & 0 & 0 \\ & \text{mmc} & \text{mcc} \\ & \cdots 1 \cdots & \\ \text{mmm} & \xrightarrow{2} & \text{mcm} \\ & \vdots & \vdots \\ & 1 & \end{array} \right) = \{s \mid s \models \varphi\}$$

Semantics of a PPAL formula φ

“All children are clean”

$$\llbracket \varphi \rrbracket = \left(\begin{array}{ccc} & \text{cmc} & \dots 1 \dots \text{ccc} \\ & \swarrow 2 & \swarrow 2 \\ \text{cmm} & \text{---} 1 & \text{ccm} & 0 \\ | & 0 & | & \dots \\ 0 & \text{mmc} & \dots 1 \dots & \text{mcc} \\ \swarrow 2 & & \swarrow 2 & \\ \text{mmm} & \text{---} 1 & \text{mcm} & \end{array} \right) = \{s \mid s \models \varphi\}$$

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Semantics of a PPAL formula φ

“After announcing there is at least one muddy child,
all the muddy children know they're muddy”

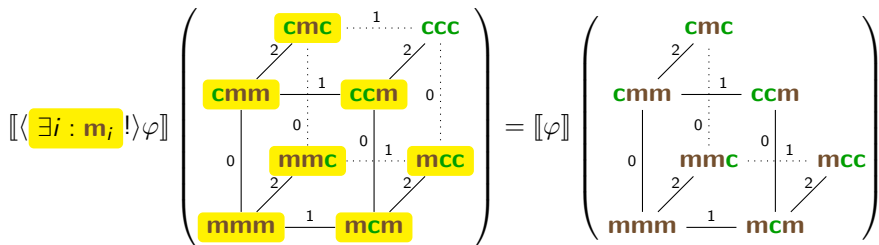
$$\varphi \equiv \forall j: m_j \rightarrow K_j m_j$$

$$\llbracket \langle \exists i: m_i ! \rangle \varphi \rrbracket = \left(\begin{array}{ccc} & \text{cmc} & \dots & 1 & \dots & \text{ccc} \\ & / \quad 2 & & & & / \quad 2 \\ \text{cmm} & \text{---} & 1 & & \text{ccm} & \text{---} & 0 \\ & | & 0 & & | & 0 \\ & & & & & & & 1 & & \text{mcc} \\ & & & & & & & / \quad 2 \\ \text{mmm} & \text{---} & 1 & & \text{mcm} & & & & & \end{array} \right)$$

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$$\begin{aligned} \llbracket \langle \exists i: m_i ! \rangle \varphi \rrbracket &= \left(\begin{array}{ccc} & \text{cmc} & \dots 1 \dots \text{ccc} \\ & \swarrow 2 & \vdots & \swarrow 2 & \vdots & \\ \text{cmm} & \xrightarrow{1} & \text{ccm} & 0 & & \\ \left| \begin{array}{c} 0 \\ 0 \end{array} \right. & & \left| \begin{array}{c} 0 \\ 1 \end{array} \right. & & & \\ & \swarrow 2 & \vdots & \swarrow 2 & & \\ \text{mmm} & \xrightarrow{1} & \text{mcm} & & & \end{array} \right) = \llbracket \varphi \rrbracket \left(\begin{array}{ccc} & \text{cmc} & \\ & \swarrow 2 & \vdots & \\ \text{cmm} & \xrightarrow{1} & \text{ccm} & \\ \left| \begin{array}{c} 0 \\ 0 \end{array} \right. & & \left| \begin{array}{c} 0 \\ 1 \end{array} \right. & \\ & \swarrow 2 & \vdots & \swarrow 2 & \\ \text{mmm} & \xrightarrow{1} & \text{mcm} & \end{array} \right) \\ &= \{ \text{cmc}, \text{mcc}, \text{ccm} \} \end{aligned}$$

Semantics of φ on a **paramaterized** system

$$\llbracket \langle \exists i : \mathbf{m}_i! \rangle \forall j : \mathbf{m}_j \rightarrow K_j \mathbf{m}_j \rrbracket \left(\begin{array}{c} \begin{array}{ccc} \mathbf{cm} & \xrightarrow{1} & \mathbf{cc} \\ 0 & | & 0 \\ \mathbf{mm} & \xrightarrow{1} & \mathbf{mc} \end{array} & \begin{array}{ccc} & \mathbf{cmc} & \xrightarrow{1} & \mathbf{ccc} \\ & 2 & | & 2 \\ \mathbf{cmm} & \xrightarrow{1} & \mathbf{ccm} & 0 \\ 0 & | & 0 & 1 \\ & 2 & \mathbf{mmc} & | & \mathbf{mcc} \\ & & & & 2 \\ \mathbf{mmm} & \xrightarrow{1} & \mathbf{mcm} & & \end{array} & \dots \end{array} \right) =$$

Semantics of φ on a **paramaterized** system

$$\llbracket \langle \exists i : \mathbf{m}_i! \rangle \forall j : \mathbf{m}_j \rightarrow K_j \mathbf{m}_j \rrbracket \left(\begin{array}{c} \begin{array}{ccc} \mathbf{cm} & \xrightarrow{1} & \mathbf{cc} \\ 0 \downarrow & & \downarrow 0 \\ \mathbf{mm} & \xrightarrow{1} & \mathbf{mc} \end{array} & \begin{array}{ccc} & \mathbf{cmc} & \xrightarrow{1} & \mathbf{ccc} \\ \mathbf{cmm} & \xrightarrow{1} & \mathbf{ccm} & \downarrow 0 \\ 0 \downarrow & & \downarrow 0 & \mathbf{mcc} \\ & \mathbf{mmc} & \xrightarrow{1} & \mathbf{mcm} \\ \mathbf{mmm} & \xrightarrow{1} & & \end{array} & \dots \end{array} \right) = \left\{ \begin{array}{l} \mathbf{mc}, \\ \mathbf{cm}, \\ \mathbf{mcc}, \\ \mathbf{cmc}, \\ \mathbf{ccm}, \\ \mathbf{mccc}, \\ \mathbf{cmcc}, \\ \mathbf{ccmc}, \\ \mathbf{cccm}, \\ \dots \end{array} \right\}$$

Semantics of φ on a **paramaterized** system

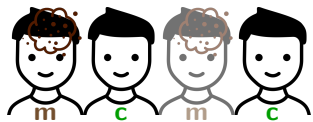
$$\llbracket \langle \exists i : \mathbf{m}_i! \rangle \forall j : \mathbf{m}_j \rightarrow K_j \mathbf{m}_j \rrbracket =$$

$$\left(\begin{array}{ccc|ccc}
 \mathbf{cm} & \xrightarrow{1} & \mathbf{cc} & & & \\
 0 & | & 0 & & & \\
 \mathbf{mm} & \xrightarrow{1} & \mathbf{mc} & & & \\
 \hline
 & & & \mathbf{cmm} & \xrightarrow{1} & \mathbf{ccm} & 0 \\
 & & & 0 & | & 0 & 1 \\
 & & & 0 & | & 2 & \mathbf{mcc} \\
 & & & \mathbf{mmm} & \xrightarrow{1} & \mathbf{mcm} & \\
 \hline
 & & & & & & \dots
 \end{array} \right) =$$

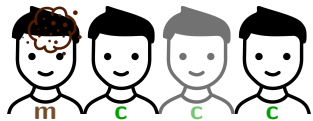
$$\left\{ \begin{array}{ccc}
 \mathbf{mc}, & \mathbf{mcc}, & \mathbf{mccc}, \\
 \mathbf{cm}, & \mathbf{cmc}, & \mathbf{cmcc}, \\
 & \mathbf{ccm}, & \mathbf{ccmc}, \\
 & & \mathbf{cccm}, \dots
 \end{array} \right\} =$$

$$\{\mathbf{c}\}^* \cdot \{\mathbf{m}\} \cdot \{\mathbf{c}\}^*$$

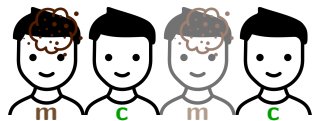
Regular Encoding



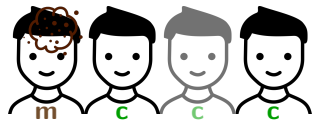
\approx



Regular Encoding



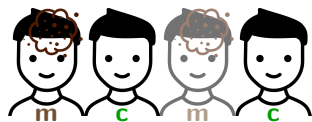
\approx



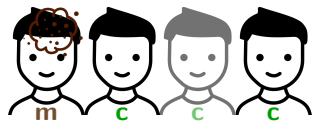
Encoded as

m	c	m	c
0	0	1	0
m	c	c	c

Regular Encoding



\sim

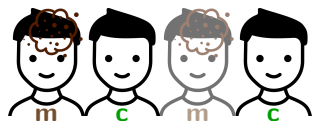


Encoded as

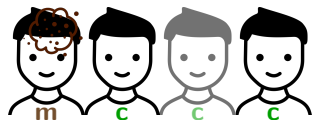
m	c	m	c
0	0	1	0
m	c	c	c

$$\in \left(\begin{array}{c} \{\mathbf{m}, \mathbf{c}\} \\ \times \\ \{0, 1\} \\ \times \\ \{\mathbf{m}, \mathbf{c}\} \end{array} \right)^*$$

Regular Encoding



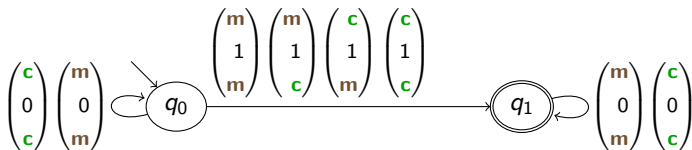
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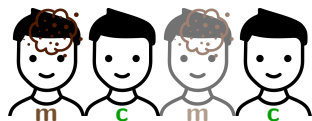
Encoded as

m	c	m	c
0	0	1	0
m	c	c	c

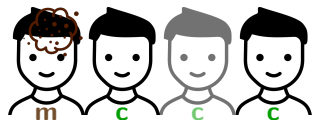
$$\in \left(\begin{matrix} \{m, c\} \\ \times \\ \{0, 1\} \\ \times \\ \{m, c\} \end{matrix} \right)^*$$



Regular Encoding



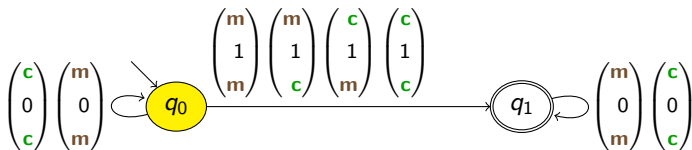
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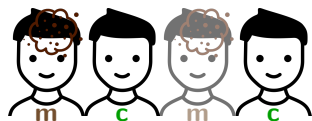
Encoded as

m	c	m	c
0	0	1	0
m	c	c	c

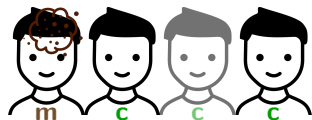
$$\in \left(\begin{matrix} \{m, c\} \\ \times \\ \{0, 1\} \\ \times \\ \{m, c\} \end{matrix} \right)^*$$



Regular Encoding



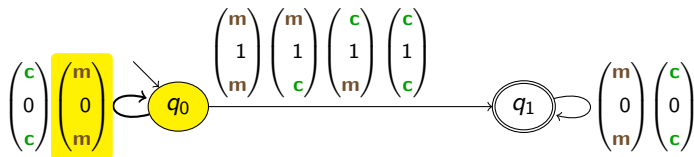
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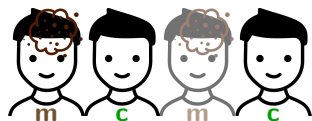
Encoded as

m	c	m	c
0	0	1	0
m	c	c	c

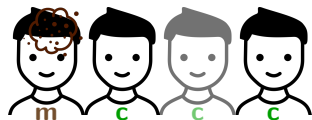
$$\in \begin{pmatrix} \{m, c\}^* \\ \times \\ \{0, 1\} \\ \times \\ \{m, c\} \end{pmatrix}$$



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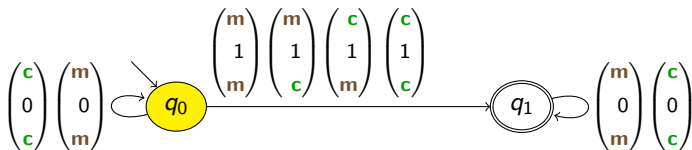
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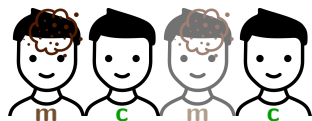
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m	c	m	c
0	0	1	0
m	c	c	c

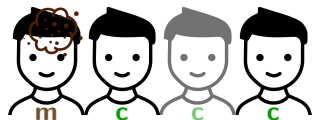
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Regular Encoding



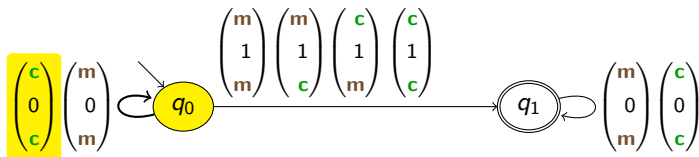
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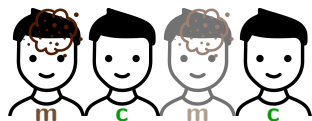
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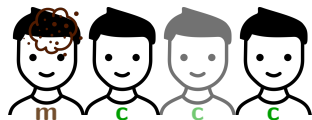
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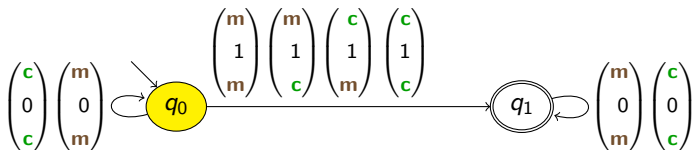
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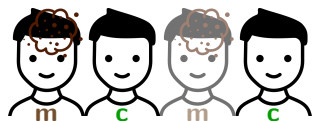
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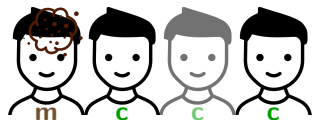
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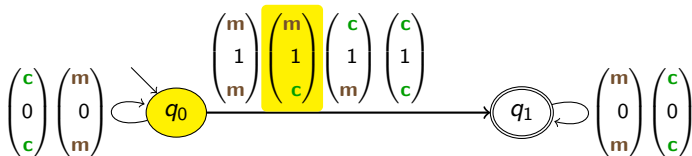
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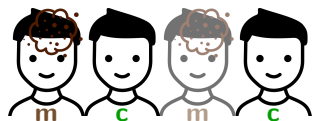
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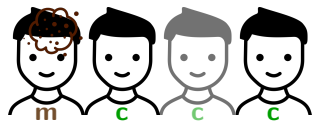
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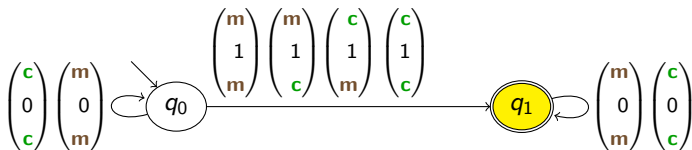
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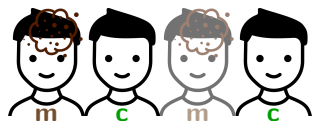
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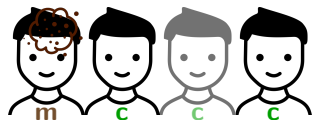
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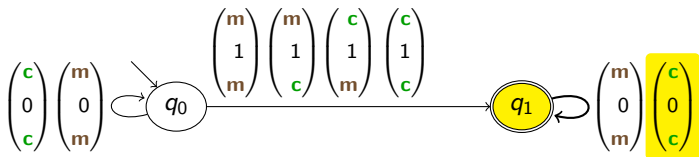
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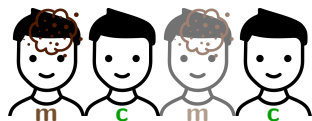
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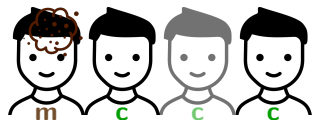
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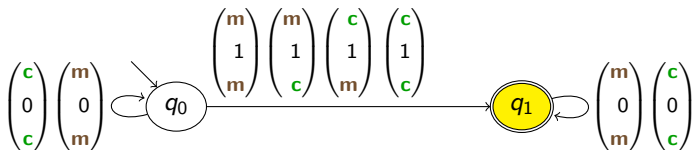
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Definition (**Regular** Kripke structure)

$\mathcal{M} = (S, \Sigma, AP, \sim, L)$ where:

- ▶ Σ finite alphabet;
- ▶ AP finite set of atomic propositions;
- ▶ $S \subseteq \Sigma^*$;
- ▶ For all $0 \leq i < |s|$, $L_i(s) \subseteq AP$;
- ▶ \sim is encoded as a **length-preserving** transducer:

$$T_{\mathcal{M}} = \left\{ s \otimes \left(\underbrace{0 \dots 0}_i \cdot 1 \cdot \underbrace{0 \dots 0}_{|s|-i-1} \right) \otimes t \mid s \stackrel{i}{\sim} t \right\}$$

Contribution: Regular Semantics of a PPAL formula

$$\left\{ \begin{array}{|c|} \hline w_1 \\ \hline 0^{i-1} 10^{n-i-1} \\ \hline w_2 \\ \hline \end{array} \middle| w_1 \stackrel{i}{\sim} w_2 \right\} \xrightarrow{\llbracket \varphi \rrbracket} \{ \boxed{w} \mid \mathcal{M}, w \models \varphi \}$$

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If \mathcal{M} is a regular Kripke structure, then $\llbracket \varphi \rrbracket(\mathcal{M})$ is a **regular language**.
Moreover, the transformation is **effective**.

PPAL model checking is **decidable**.

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Application Verify the parameterized solution of van Ditmarsch (2003) for $3+x+1$ cards.

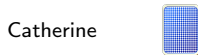
Another Example: Russian card problem, with $3 + 3 + 1$

cards:



Alice's goal:

- Making Bob aware of her hand;
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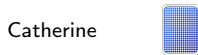
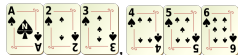


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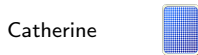
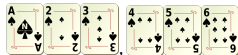


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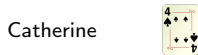


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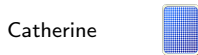
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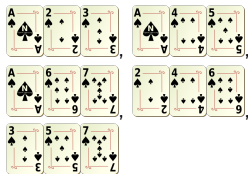


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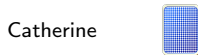
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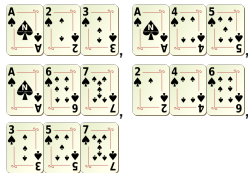


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2: Iterated Announcement

- ▶ Safety Regular Model Checking
- ▶ Active Learning approach
- ▶ Learning Disappearance Relation

How many announcements? Iterated Announcement

How many announcements before a (sub)formula holds?

Muddy Children Example:

One muddy child \rightarrow 1 PA;

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Is the system *Safe*? That is to say:

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Decidability:

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Decidability: **No**

Safety Analysis Strategies

Some techniques:

- ▶ Regular Model Checking **Using Inference** of Regular Languages (Habermehl and Vojnar, 04)
- ▶ Parameterized verification through **view abstraction** (Abdulla, Haziza, and Holik, 15)
- ▶ Regular Model Checking using **Widening Techniques** (Touili, 01)
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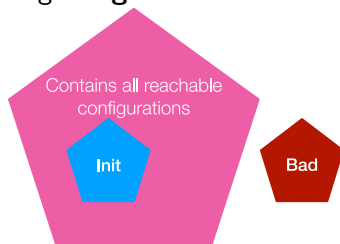
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Most of these are based on finding a **regular invariant**:

Definition

$I \in \text{Reg}(\Sigma)$ such that

1. $\text{Init} \subseteq I$;
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Active Learning: the 20 questions game example

“Think of a character, object or animal, and let me ask you questions.”

The **learner** asks arbitrary questions

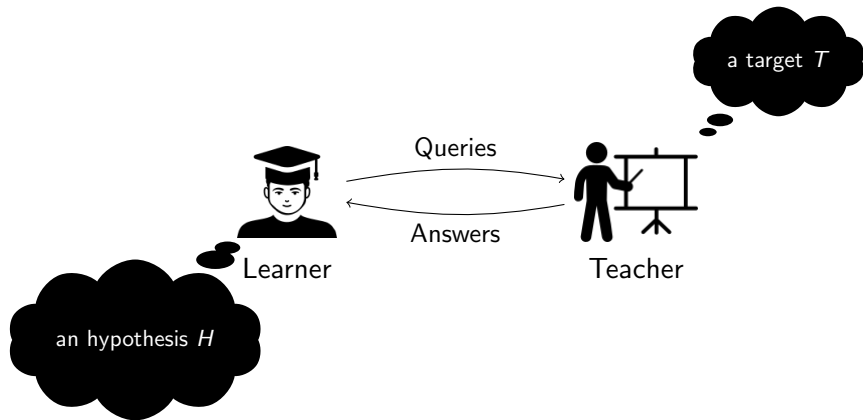


The **teacher** answers by YES/NO/MAYBE.

<https://akinator.com>

https://en.wikipedia.org/wiki/Twenty_questions

Active Machine Learning



The **Concept class** \mathcal{C} describes all possible values of $H \in \mathcal{C}$;

Goal for Learner: find $H = T$ or at least $H \approx T$;

Active learning: the learner chooses the questions.

Regular Language Active Learning (Angluin's L^* , 87)

For regular machine learning, the concept to learn is a **finite automaton** \mathcal{H} :

- ▶ **concept class** \mathcal{C} is the set of all finite automata over Σ
- ▶ The **target** is a language $L \subseteq \Sigma^*$.

$$\text{Goal: } \mathcal{L}(\mathcal{H}) = L$$

Two types of queries:

- ▶ **Membership queries**: “Does $w \in L$?” for some given $w \in \Sigma^*$
Answer: YES or NO;
- ▶ **EQ**ivalence queries: “Is $\mathcal{L}(\mathcal{H}) = L$?” for some given DFA \mathcal{H}
Answer: YES or NO and a **counterexample** $w \in \mathcal{L}(\mathcal{H}) \Delta L$

Symmetric Difference of A and B : $A \Delta B := A \setminus B \cup B \setminus A$.

Example of a Learner: learnlib

Java Library for active learning of regular languages:

<https://learnlib.de/>

← → ↻ 🏠 github.com/LearnLib/learnlib/wiki/instantiating-a-simple-learning-setup

This whole procedure can be implemented as follows:

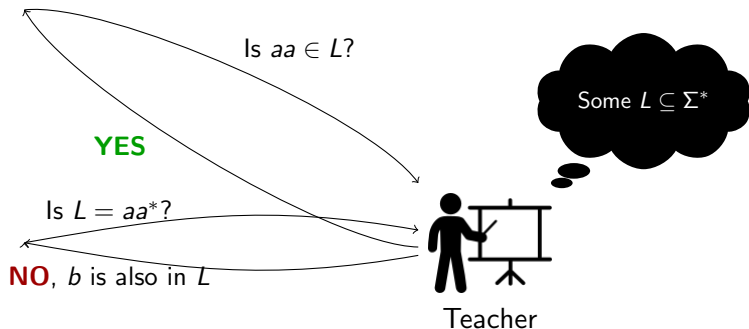
```
DefaultQuery<Input, Word<String>> counterexample = null;
do {
    if (counterexample == null) {
        learner.startLearning();
    } else {
        boolean refined = learner.refineHypothesis(counterexample);
        if (!refined) {
            System.err.println("No refinement effected by counterexample!");
        }
    }

    counterexample = eqoracle.findCounterExample(learner.getHypothesisModel(), alphabet);
} while (counterexample != null);

// from here on learner.getHypothesisModel() will provide an accurate model
```

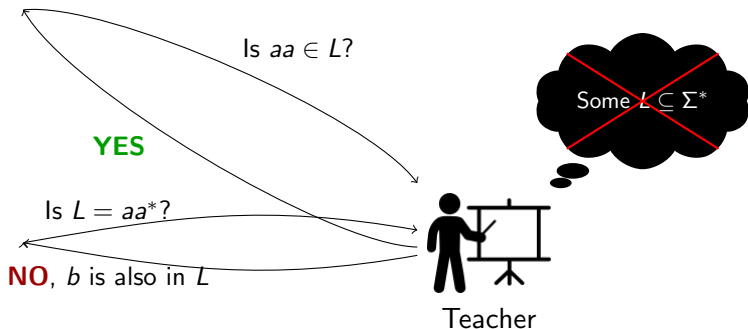
The do-while loop will be executed as long as counterexamples are discovered by the equivalence oracle. Once the loop terminates the hypothesis model provided by the learner is guaranteed to be an exact representation of the target system if the equivalence oracle is guaranteed to find any behavioral mismatches between the hypothesis and the target system (which is the case in this example).

Implementation of a Teacher



A teacher provides **Oracles** (here: a **M** oracle and a **EQ** oracle).

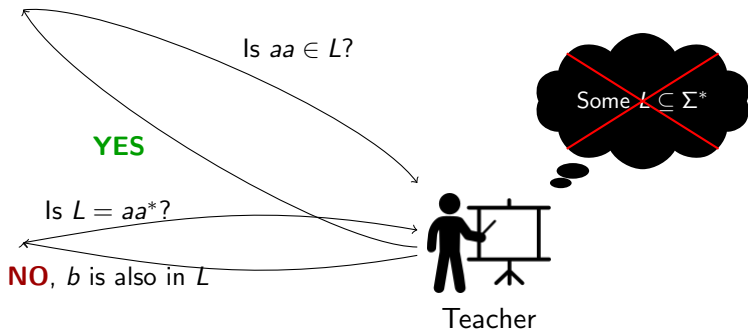
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A teacher provides **Oracles** (here: a **M** oracle and a **EQ** oracle).

- ▶ In practice, the teacher may **not know the target** L , this is fine as long as he **can answer the queries**.
- ▶ The target *might* not be **regular**. In this case, the learner will **never manage** to find a suitable automaton \mathcal{H} .

A safety teacher

A regular invariant is defined as first-order properties.

Definition (Regular Invariant)

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Oracle for learning some target I :

- ▶ **M**embership: Given w , check whether $\exists w' \in Init : w' \sim^* w$.
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Uncovered here: there might be more than one invariant, so there is some slack in the oracle's answer (for membership queries, and for counterexample in (3)).

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Theorem

Model checking of a regular Kripke structure against:

- ▶ a PPAL formula is **decidable**;
- ▶ a $PPAL^*$ formula is **undecidable**.

We design a **semi-decision** procedure.

Disappearance relation for φ

$s \preceq t$ if, and only if, $\forall k, s \in S_k \Rightarrow t \in S_k$


where S_k state space left after k announcements $\langle \varphi! \rangle$.

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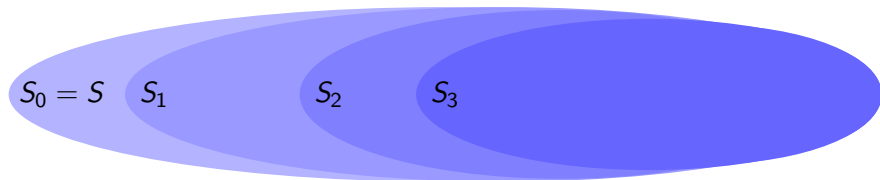
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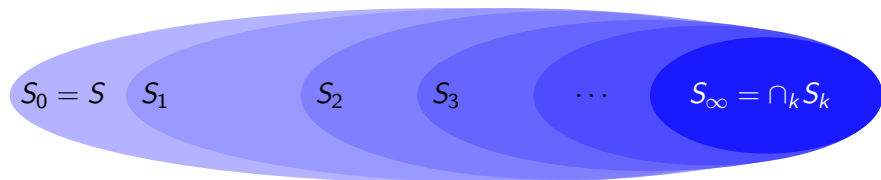
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Abstracting away from the iteration

Claim: $\mathcal{M}, s \models \langle \varphi! \rangle^* \psi$ if, and only if,

$$\underbrace{\exists t \notin S_\infty \wedge t \preceq s}_{\exists k \in \mathbb{N}} \quad \mathcal{M} \upharpoonright_{\underbrace{\{u \mid t \preceq u\}}_{S_k}}, s \models \psi$$

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Consequence: if \mathcal{M} and $L_{\preceq} = \left\{ \frac{s}{t} \mid s \preceq t \right\}$ are **regular**,

then $\llbracket \langle \varphi! \rangle^* \psi \rrbracket(\mathcal{M})$ is **effectively regular**.

Contribution: Learning \preceq

Theorem

*Given some PPAL formula φ , and \preceq its disappearance relation.
The learning procedure terminates and returns L_{\preceq} if, and only if,
 L_{\preceq} is **regular**.*

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We run L^* algorithm (Angluin, 87) by implementing:

1. A **membership oracle**: given $s, t \in S$, $s \stackrel{?}{\preceq} t$;
2. An **equivalence oracle**: given L' regular, does $L' = L_{\preceq}$ and if not, provide **counterexample** $w \in L \setminus L_{\preceq} \cup L_{\preceq} \setminus L$.

Theorem (Unique Characterization)

For $R \subseteq S \times S$, $R = \preceq$, iff:

1. **Reflexive**

and

2. **Transitive**

and

3. **Total**

and

4. **Some “F” property**

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For $R \subseteq S \times S$, $R = \preceq$, iff:

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- (1) s **really** disappears;
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$$4. \quad \forall s \begin{cases} \text{either (1) } \forall t : (s, t) \in R \rightarrow (t, s) \notin R \leftrightarrow t \in F(sR \cdot) \\ \text{or (2) } \forall t : (s, t) \in R \rightarrow (t, s) \in R \wedge t \in F(sR \cdot) \end{cases}$$

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→ **Effective and Uniformly Regular**

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3: Applications and extensions

Muddy Children

“After **arbitrary** but **finitely** many rounds, all the muddy children know they're muddy.”

$$\varphi = \langle \exists i : \mathbf{m}_i! \rangle \underbrace{\langle \exists i : \mathbf{m}_i \wedge \neg K_i \mathbf{m}_i! \rangle}_{\psi}^* \perp$$

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$$\varphi = \langle \forall i, \mathbf{m}_{i+1} \rightarrow \mathbf{m}_i! \rangle \langle \exists i : \mathbf{m}_i! \rangle \underbrace{\langle \exists i : \mathbf{m}_i \wedge \neg K_i \mathbf{m}_i! \rangle^*}_{\psi} \perp$$

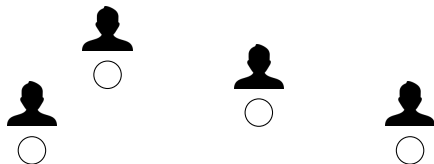
$$L_{\perp} = \left\{ \begin{array}{|c|} \hline \mathbf{s} \\ \hline \mathbf{t} \\ \hline \end{array} \middle| |s|_{\mathbf{m}} \leq |t|_{\mathbf{m}} \wedge s, t \in \{\mathbf{m}\}^* \cdot \{\mathbf{c}\}^* \right\} \subseteq (\{\mathbf{m}, \mathbf{c}\} \times \{\mathbf{m}, \mathbf{c}\})^*$$

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Dining Cryptographer algorithm

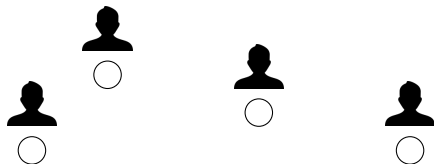


- ▶ Every cryptographer i has a private boolean p_i .
- ▶ Goal: Decide whether $\sum_i p_i > 0$ without disclosing the p_i 's

Algorithm:

- ▶ For each i , sample a boolean c_i **shared** between i and $i + 1 \% N$.
- ▶ Publicly announce the result of $c_i \oplus c_{i-1 \% N} \oplus p_i$
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Simplifications: non-probabilistic setting, sequential announcements.

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How to **mechanize** these announcements, to verify the following properties?

Formalization

Private Variables: $(p_i)_{i \in [1;M]} \in \{0, 1\}^M$

Goal1: “Everyone knows whether someone paid”

$$\forall i, (K_i \exists j : p_j) \vee (K_i \forall j : \neg p_j)$$

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Announcement of agent i : **result** of computation

$$r_i = c_i \oplus c_{i+1 \% N} \oplus p_i$$

Agents compute $\bigoplus_i r_i = \bigoplus_i p_i$

Public Announcement Whether

We introduce the new construct $\langle \varphi !! \rangle \psi$.

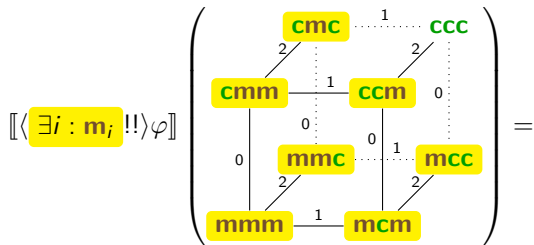
“After announcing **whether** there is at least one muddy child, φ ”

$$\llbracket \langle \exists i : m_i !! \rangle \varphi \rrbracket = \left(\begin{array}{ccc} & \text{cmc} & \text{ccc} \\ & \cdots 1 \cdots & \\ \text{cmm} & \xrightarrow{1} & \text{ccm} \\ & \vdots & \vdots \\ & 0 & 0 \\ & \text{mmc} & \text{mcc} \\ & \cdots 1 \cdots & \\ \text{mmm} & \xrightarrow{1} & \text{mcm} \\ & \vdots & \vdots \\ & 0 & 0 \end{array} \right) =$$

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The diagram illustrates the semantic equivalence between the announcement operator $\langle \exists i : m_i !! \rangle \varphi$ and the formula φ . The left side shows a game tree for the announcement operator, and the right side shows a game tree for the formula. The trees are identical, with nodes labeled with combinations of 'm' (muddy) and 'c' (clean) for each of three children. Edges are labeled with 0, 1, or 2, representing the number of muddy children. The nodes are arranged in a grid-like structure with vertical and horizontal edges, and diagonal edges labeled with 2. The nodes are: top row (cmc, CCC), second row (cmm, CCM), third row (mmc, MCC), and bottom row (mmm, mcm).

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The diagram illustrates the equivalence between the public announcement operator and the original formula. The left side shows a grid of states (mmm, mmm, mmm, mmm) with transitions labeled with 0, 1, 2. The right side shows the same grid but with some states (cmc, ccm, mmc, mcc) highlighted in green, representing the states where the announcement is made.

Good news

- ▶ Still regular: $\llbracket \langle \varphi !! \rangle \psi \rrbracket (\mathcal{M}) = \llbracket \psi \rrbracket (\dots)$
- ▶ $\langle \varphi !! \rangle^* \psi$ can be computed with a disappearance relation **on pair of states**:

$$L_{\leq} \subseteq (\Sigma' \times \Sigma')^* \quad \text{where } \Sigma' = \Sigma \times \{0, 1\} \times \Sigma$$

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or one single formula $\varphi(i)$ parameterized by $i \in \text{Agt}$.

Theorem (Addressed in Felix Thoma's BA thesis)

There exists φ' without free variables, such that

$$\langle c_0 \oplus c_1 \oplus p_0!! \rangle \langle c_1 \oplus c_2 \oplus p_1!! \rangle \dots \langle c_N \oplus c_0 \oplus p_0!! \rangle \varphi_{\text{correct}} \equiv \langle \varphi'!! \rangle^* \varphi_{\text{correct}}$$

Key ideas:

- ▶ Track the announcements already been made, by *evaluating the current common knowledge*.
- ▶ The same announcement should be made from all the states, **at the same time**.
- ▶ Solution 1: common knowledge operator \sim^* (similar to safety analysis).

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- ▶ Solution 1: common knowledge operator \sim^* (similar to safety analysis).
- ▶ Solution 2: introducing $All(\varphi)$ operator, whose semantics is regular.

Summary

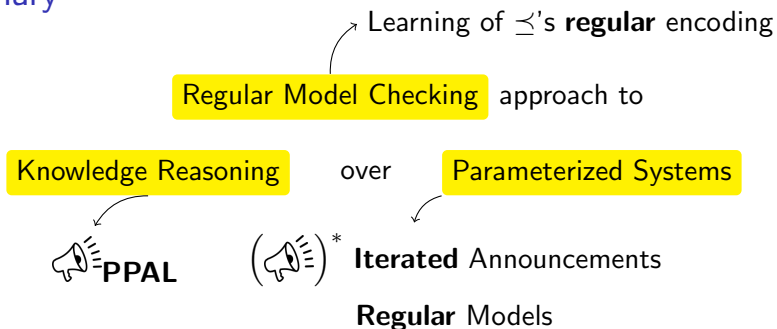
Regular Model Checking approach to

Knowledge Reasoning

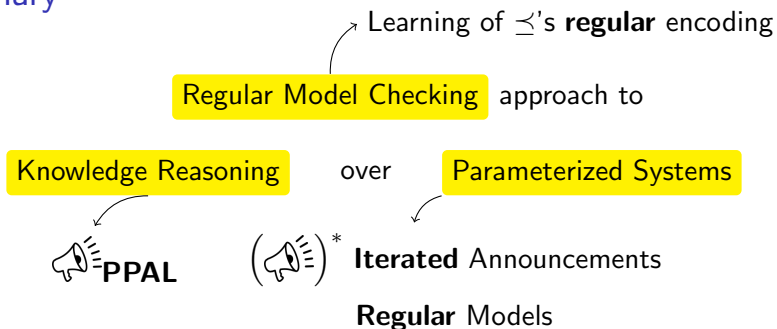
over

Parameterized Systems

Summary



Summary



Future work:

- ▶ **Dynamic** Epistemic Logic (more systematic way to *dining cryptographer*, stochastic behaviours).
- ▶ **Planning**: how to synthesize announcements (card protocols).
- ▶ **Mechanize** the symmetry reductions (*Parikh images*).
- ▶ More succinct models (expressing fixed point in *MONA*).

Thanks for your attention