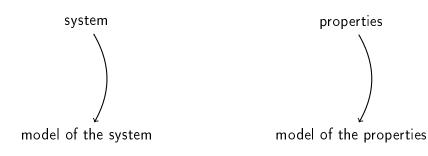
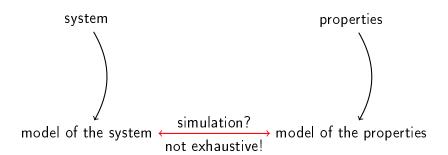
### An Introduction to Model Checking

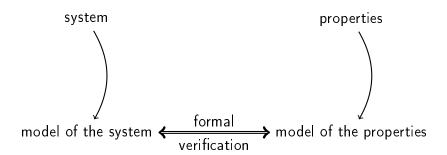
Alexandre Duret-Lutz

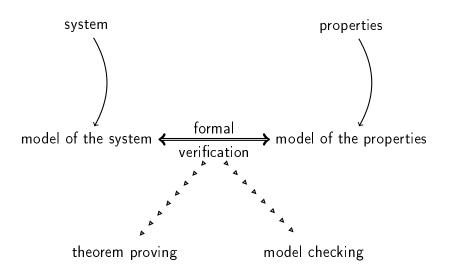
23 August 2010 IIT Jodhpur

http://www.lrde.epita.fr/~adl/ens/mc/iitj.pdf









# Theorem Proving

- Describe the system in a way that allows reasoning
- Prove property by logical reasoning

This can be entirely manual, or using the help of a theorem prover (e.g. Coq) that is not fully automatic.

Problem: it is hard to produce a counterexample when a theorem is false.

Research work in the area: new proof systems, study of the expressive power of various logics...

## Model checking

An automatic approach to formal verification.

An exhaustive verification of all behaviors of a model.

The catch: the model has to be abstract enough (i.e. not too detailed) to allow its complete exploration.

### Example: an Algorithm for Mutual Exclusion

Global variables:  $req_P$  and  $req_Q$ .

#### Process P (infinite loop)

- 1  $req_P \leftarrow 1$
- 2.  $wait(req_Q = 0)$
- 3. Critical Section
- 4.  $req_P \leftarrow 0$

#### Process Q (infinite loop)

- 1.  $req_Q \leftarrow 1$
- 2.  $wait(req_P = 0)$
- 3. Critical Section
- 4.  $req_Q \leftarrow 0$

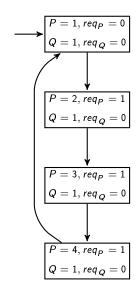
Initial state: P = 1, Q = 1,  $req_P = 0$ ,  $req_Q = 0$ .

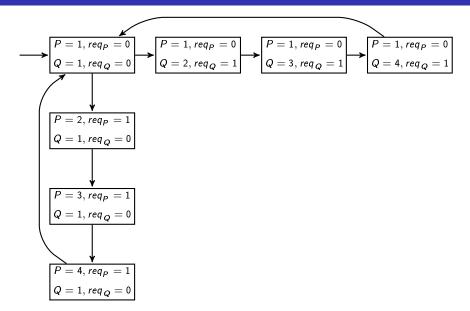
#### Properties to check:

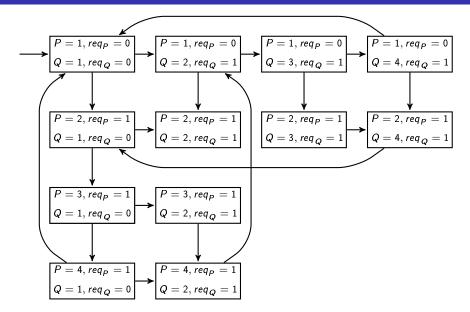
- At any time, there is at most one process in Critical Section.
- Any process requesting entrance to the CS will eventually enter it.
- The order of entrances to the CS should follow the order of requests.

$$\longrightarrow P = 1, req_P = 0$$

$$Q = 1, req_Q = 0$$







### Property 1

At any time, there is at most one process in CS.

Translation: there is no state with P=3 and Q=3.

It is true.

To check this property we need to explore the entire state space once. We only need to know the set of states, not how they are connected.

### Property 2

#### Any process requesting entrance to CS will eventually enter it.

Translation: any execution that visits a state with P=2 should later visit a state with P=3; likewise for Q=2 and Q=3.

It is false.

The state 
$$\begin{bmatrix} P=2, req_P=1 \\ Q=2, req_Q=1 \end{bmatrix}$$
 has no successor (it is a deadlock).

To check this property, we have to know the entire graph (states alone are not enough).

#### Property 3

The order of entrances into the CS follow the order of requests.

Translation: any execution path that sees a state with  $P=2 \land Q=1$  should not visit any state with Q=3 before visiting a state with P=3 (+ symmetric property for Q).

It is true if we ignore the deadlock.

Same kind of verification as property 2.

#### A Formalization

- Represent the system using a finite automaton.
- Represent the property using a temporal logic formula.
- To compare these two objects, convert the temporal logic formula into an automaton.
- Some work on the two automata will tell us if they are "compatible".

### Propositional Logic: the Present

Propositional logic formulas can be use characterize one instant.

- r: red light on
- y: yellow light on
- g: green light on

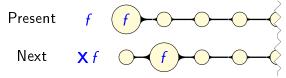
$$r \wedge y \wedge g = 0$$
,  $r \wedge \neg y \wedge \neg g = 0$ ,  $\neg r \wedge \neg y \wedge g = 0$ ,  $\neg r \wedge \neg y \wedge \neg g = 0$ .

How can we say that the system is not always

 $\Rightarrow$  we need to make time apparent in the formula

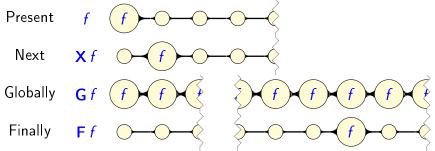
# Linear-time Temporal Logic (LTL) Operators

Let f and g be two propositional logic formulas:



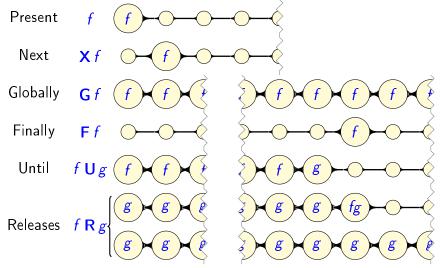
# Linear-time Temporal Logic (LTL) Operators

Let f and g be two propositional logic formulas:



# Linear-time Temporal Logic (LTL) Operators

Let f and g be two propositional logic formulas:



### LTL: Examples

```
Next
         X f f is true at next instant
        G f it true at all instants
Globally
 Finally \mathbf{F} f will be true eventually (now or in the future)
  Until f U g
                f stays true until g becomes true
```

$$\neg \mathbf{G}(r \wedge \neg y \wedge \neg g)$$

the system is not always

$$\mathbf{G}((\neg r \wedge y \wedge \neg g) \rightarrow \mathbf{X}(r \wedge \neg y \wedge \neg g))$$
: always imm. flw'd by

**G** 
$$F(\neg r \land \neg y \land g)$$
:

the systems is infinitely often

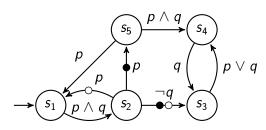
These formulas can be translated into automata.

#### TGBA: Generalized Büchi Automata

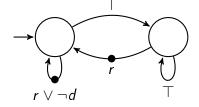
A Transition-based Generalized Büchi Automata has:

- a set of states, with a designated initial state,
- a set of transitions between these states, labeled by propositional logic formulas,
- a set of sets of transitions, called acceptance sets.

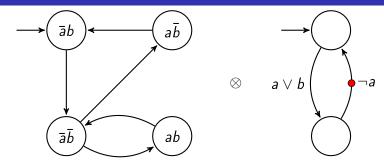
An infinite path in this automaton is accepted if it visits infinitely often a transition for each acceptance sets.



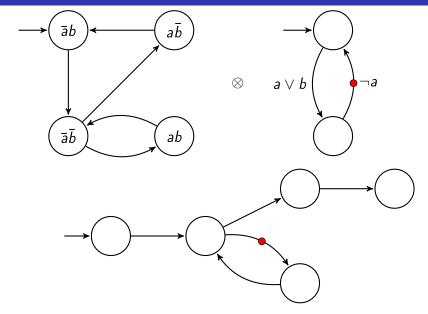
# Example of TGBA for $G(d \rightarrow F r)$



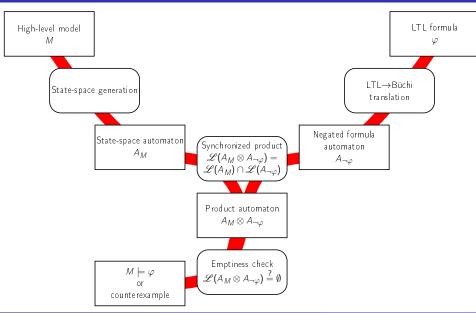
# Product between a System and a TGBA



# Product between a System and a TGBA



# Automata Theoretic Approach to Model Checking



# Tableau Rules for Propositional Logic

formula set	1 <sup>st</sup> child	2 <sup>nd</sup> child
$\Gamma \cup \{\neg \top\}$	$\Gamma \cup \{\bot\}$	
$\Gamma \cup \{  eg \bot \}$	$\Gamma \cup \{ op\}$	
$\Gamma \cup \{\neg \neg f\}$	$\Gamma \cup \{f\}$	
$\Gamma \cup \{f \land g\}$	$\Gamma \cup \{f,g\}$	
$\Gamma \cup \{f \lor g\}$	$\Gamma \cup \{f\}$	$\Gamma \cup \{g\}$
$\Gamma \cup \{\neg (f \land g)\}$	$\Gamma \cup \{\neg f\}$	$\Gamma \cup \{ \neg g \}$
$\Gamma \cup \{\neg (f \vee g)\}$	$\Gamma \cup \{\neg f, \neg g\}$	

### Tableau for $\neg \varphi$ with $\varphi = \neg (\neg A \lor B) \lor (\neg (A \land C) \lor (B \land C))$

$$\{\neg(\neg(\neg A \lor B) \lor (\neg(A \land C) \lor (B \land C)))\}$$

$$\{\neg\neg(\neg A \lor B), \neg(\neg(A \land C) \lor (B \land C))\}$$

$$\{\neg A \lor B, \neg(\neg(A \land C) \lor (B \land C))\}$$

$$\{\neg A \lor B, \neg\neg(A \land C), \neg(B \land C)\}$$

$$\{\neg A \lor B, A \land C, \neg(B \land C)\}$$

$$\{\neg A \lor B, A, C, \neg(B \land C)\}$$

$$\{\neg A \lor B, A, C, \neg(B \land C)\}$$

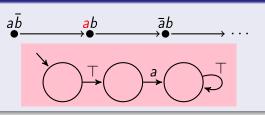
$$\{\neg A \lor B, A, C, \neg(B \land C)\}$$

$$\{B, A, C, \neg B\}$$

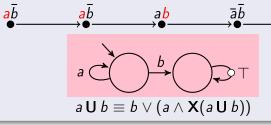
$$\{B, A, C, \neg C\}$$

#### LTL and Automata









# Tableau Rules for Propositional Logic

formula set	1 <sup>st</sup> child	2 <sup>nd</sup> child
$\Gamma \cup \{\neg \top\}$	$\Gamma \cup \{oldsymbol{\perp}\}$	
$\Gamma \cup \{  eg \bot \}$	$\Gamma \cup \{ op\}$	
$\Gamma \cup \{\neg \neg f\}$	$\Gamma \cup \{f\}$	
$\Gamma \cup \{f \wedge g\}$	$\Gamma \cup \{f,g\}$	
$\Gamma \cup \{f \lor g\}$	$\Gamma \cup \{f\}$	$\Gamma \cup \{g\}$
$\Gamma \cup \{\neg (f \land g)\}$	$\Gamma \cup \{ \neg f \}$	$\Gamma \cup \{ \neg g \}$
$\Gamma \cup \{\neg (f \vee g)\}$	$\Gamma \cup \{\neg f, \neg g\}$	

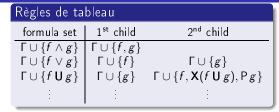
## Tableau Rules for Propositional Logic

formula set	1 <sup>st</sup> child	2 <sup>nd</sup> child
$\Gamma \cup \{\neg \top\}$	$\Gamma \cup \{oldsymbol{\perp}\}$	
$\Gamma \cup \{  eg \bot \}$	$\Gamma \cup \{ op\}$	
$\Gamma \cup \{\neg \neg f\}$	$\Gamma \cup \{f\}$	
$\Gamma \cup \{f \wedge g\}$	$\Gamma \cup \{f,g\}$	
$\Gamma \cup \{f \lor g\}$	$\Gamma \cup \{f\}$	$\Gamma \cup \{g\}$
$\Gamma \cup \{\neg (f \land g)\}$	$\Gamma \cup \{\neg f\}$	$\Gamma \cup \{ \neg g \}$
$\Gamma \cup \{\neg (f \lor g)\}$	$\Gamma \cup \{\neg f, \neg g\}$	
$\Gamma \cup \{\neg X f\}$	$\Gamma \cup \{X \neg f\}$	
$\Gamma \cup \{f \cup g\}$	$\Gamma \cup \{g\}$	$\Gamma \cup \{f, \mathbf{X}(f \cup g), P g\}$
$\Gamma \cup \{\neg (f \cup g)\}$	$\Gamma \cup \{\neg f, \neg g\}$	$\Gamma \cup \{\neg g, \mathbf{X} \neg (f \mathbf{U} g)\}$

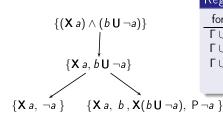
Pg is a promise that g will be fulfilled

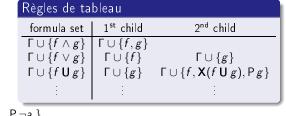
# Tableau for $(X a) \wedge (b \cup \neg a)$

$$\{(X a) \wedge (b U \neg a)\}$$

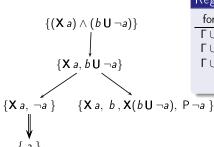


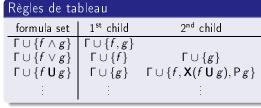
# Tableau for $(X a) \wedge (b U \neg a)$



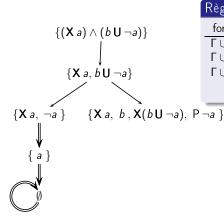


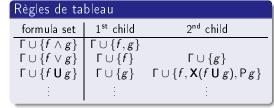
# Tableau for $(X a) \land (b \cup \neg a)$



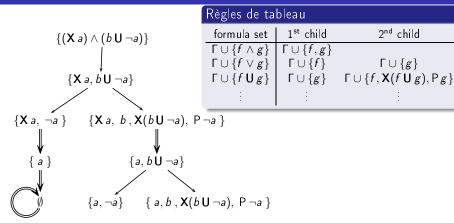


# Tableau for $(X a) \land (b \cup \neg a)$



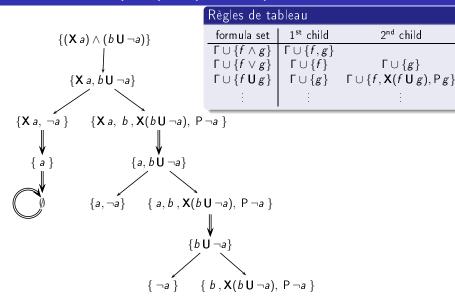


#### Tableau for $(X a) \land (b \cup \neg a)$

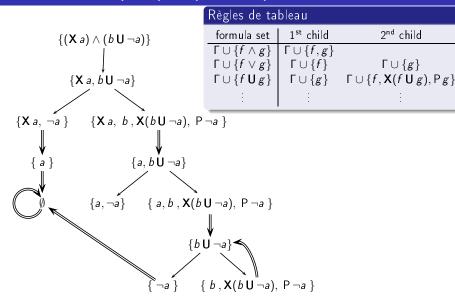


2nd child

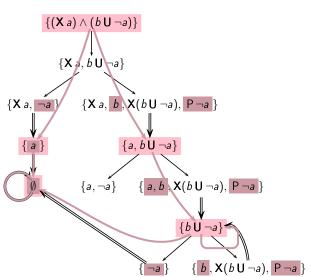
#### Tableau for $(X a) \wedge (b \cup \neg a)$

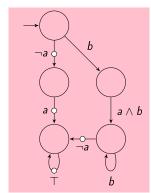


#### Tableau for $(X a) \wedge (b U \neg a)$

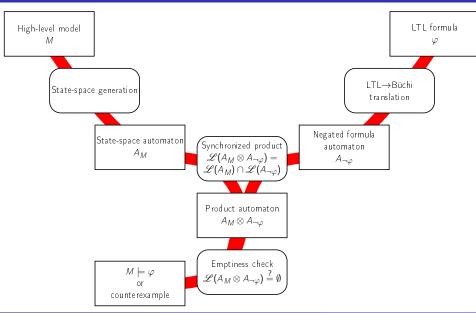


### $(X a) \land (b \cup \neg a)$ into TGBA

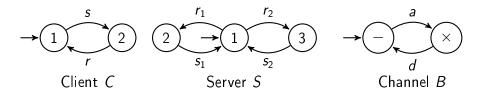




## Automata Theoretic Approach to Model Checking



#### Ex.: clients/server with synchronized automata

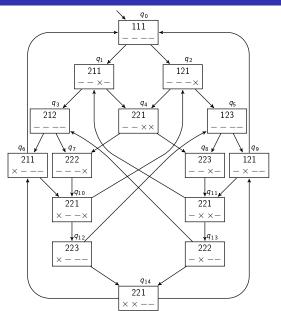


Synchronization rules for the system  $\langle C, C, S, B, B, B, B \rangle$ :

- $\langle s, ., ., ., ., a, . \rangle$
- (2) $\langle ., s, ., ., ., ., a \rangle$
- (3) $\langle r, .., .., d, .., .. \rangle$
- (4) $\langle .., r, .., d, .., .. \rangle$
- (5) $\langle .,.,r_1,..,d,.. \rangle$
- (6) $\langle$  .,., $s_1$ , a,.,.,.
- $\langle \ldots, \ldots, r_2, \ldots, \ldots, d \rangle$
- $\langle \ldots, \ldots, s_2, \ldots, a, \ldots, \ldots \rangle$

If a client sends a request, will he always get an answer?

#### State space for this example



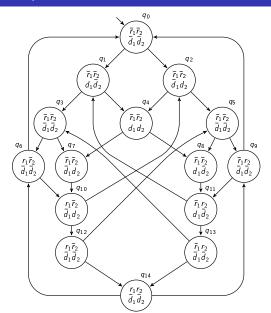
#### Atomic properties

We will write properties regarding sending and receiving messages: Let  $AP = \{a_1, a_2, r_1, r_2\}$  with:

- $a_1$ : an answer is on its way between S and  $C_1$
- $a_2$ : an answer is on its way between S and  $C_2$
- $r_1$ : a request is on its way between  $C_1$  and S
- ullet  $r_2$ : a request is on its way between  $C_2$  and S

The property "if a client sends a request, he will get an answer" can be rewritten as " $\forall i \in \{1,2\}$  an execution that visits a state where  $r_i$  is true will visit a state where  $a_i$  is true."

#### Kripke Structure for this example



#### Exploring the Kripke Structure

"an execution that visits a state where  $r_i$  is true will visit a state where  $a_i$  is true." In LTL:  $G(r_i \rightarrow F a_i)$ . (by symmetry on the model, let's deal only with i = 1).

We are looking for a counterexample: an execution that visits a state where  $r_1$  is true and which will never verify  $a_1$  from then on. In LTL:

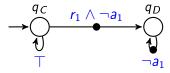
$$\neg \mathsf{G}(\mathit{r}_1 \to \mathsf{F} \mathit{a}_1) = \mathsf{F}(\mathit{r}_1 \land \mathsf{G} \neg \mathit{a}_1)$$

#### Exploring the Kripke Structure

"an execution that visits a state where  $r_i$  is true will visit a state where  $a_i$  is true." In LTL:  $\mathbf{G}(r_i \to \mathbf{F} \, a_i)$ . (by symmetry on the model, let's deal only with i=1).

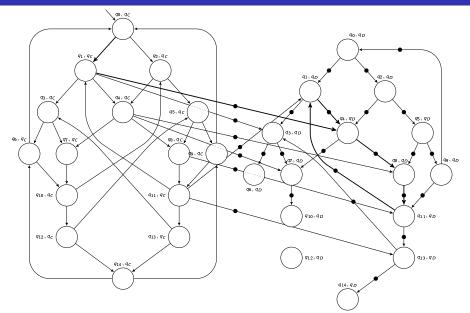
We are looking for a counterexample: an execution that visits a state where  $r_1$  is true and which will never verify  $a_1$  from then on. In LTL:  $\neg G(r_1 \rightarrow F a_1) = F(r_1 \land G \neg a_1)$ 

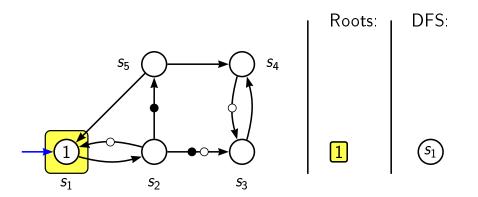
Such a counterexample can be represented by a (transition-based) Büchi automaton:

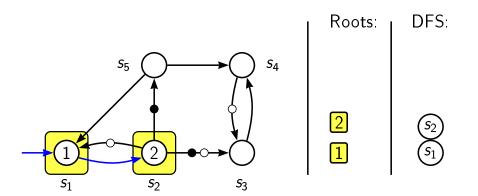


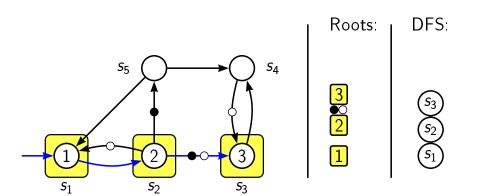
Where accepting runs must visit transitions with • infinitely often.

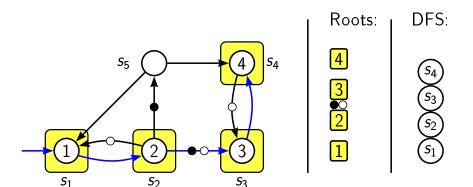
# Synchronized Product

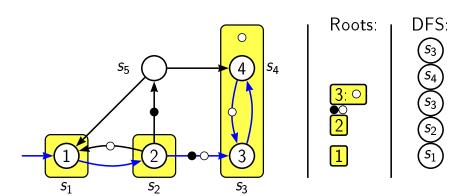


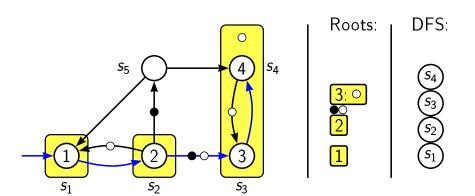


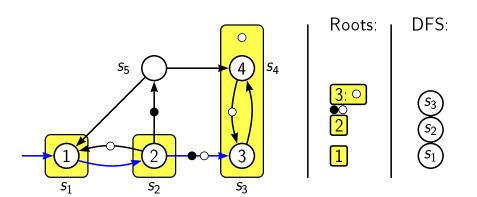


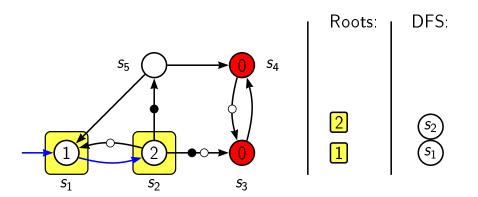


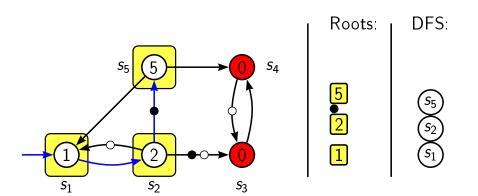


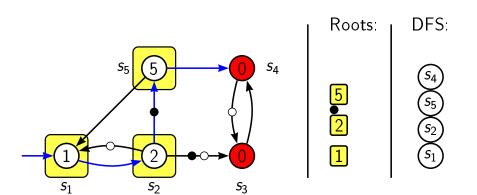


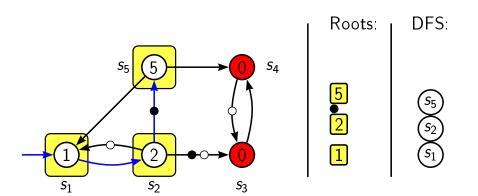


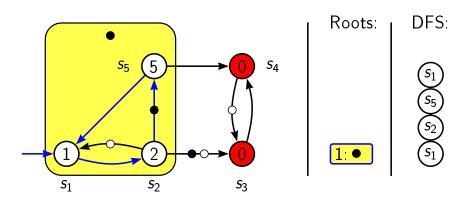


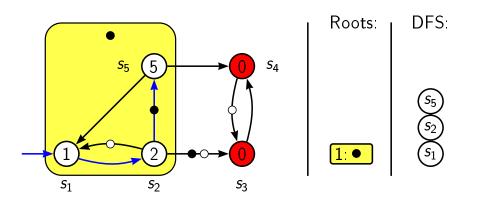


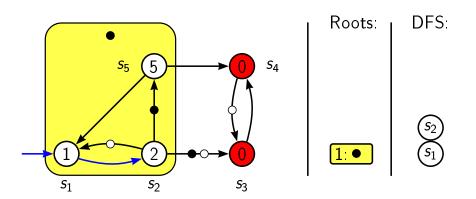


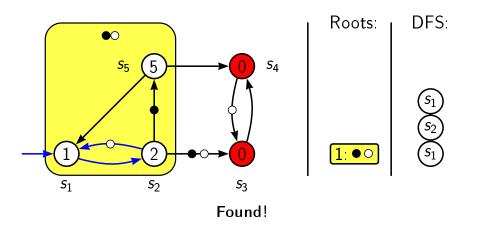




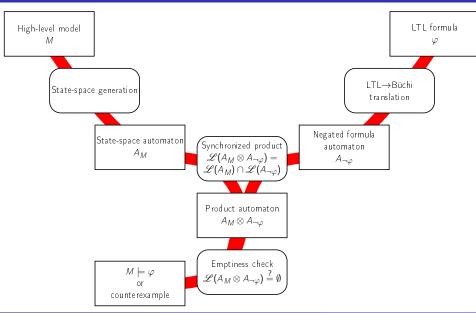








## Automata Theoretic Approach to Model Checking



#### Conclusion

- Büchi automata can be used to represent sets (finite or infinite)
  of infinite behaviors. Some operations are easy to perform on
  these sets: union, intersection, and emptiness check. Some are
  harder (e.g. complementation, universality check)
- By reducing the verification problem to some operations between automata, we actually obtained an efficient verification procedure.
- Bottleneck: translating a formula of size n can lead to a TGBA of size  $2^{O(n)}$ . The size of the product of two automata is bounded by the product of the sizes, so it is important to have small automata on both sides. Emptiness check is linear in the size of the product.

For CSE students: the automata seen in ToC are simpler because they recognize finite words. Yet they allow similar operations and applications.