

# GPU Computing

## Patterns for massively parallel programming (part 2)

### Histograms

---

E. Carlinet, J. Chazalon {firstname.lastname@lrde.epita.fr}

April 22

EPITA Research & Development Laboratory (LRDE)



Lab reminder

Simple parallel histogram

Parallel algorithm using output privatization

Summary

Lab reminder

---

During the practice session, you ~~will have~~ had to compute the **cumulated histogram** of the image.

There are two major steps:

1. Compute the histogram  $H$ :  
count the number of occurrences of each value within the image.
2. Compute the cumulated histogram  $C$ :  
sum histogram values such that  $C[i] = \sum_{k=0}^i H[k]$ .

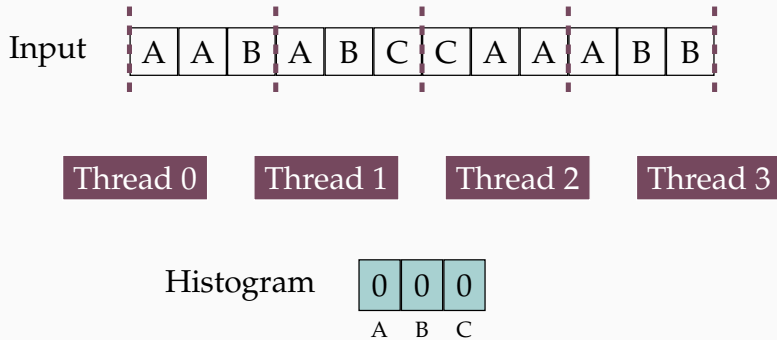
We will see how to compute those elements with **efficient parallel algorithms**.

## Simple parallel histogram

---

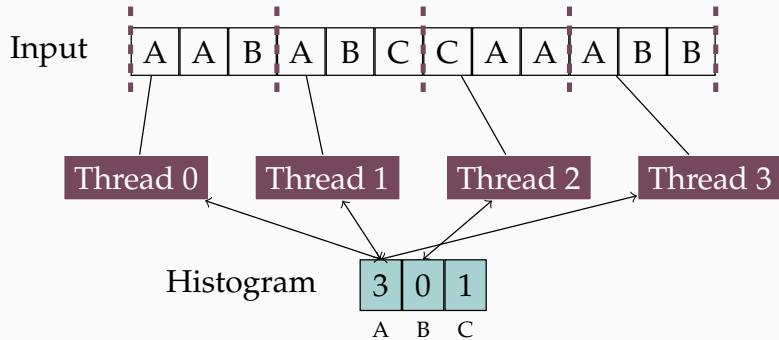
## The very wrong way

A wrong approach consists in **sectioning** the input, i.e. assigning a chunk of the input to each thread.



## The very wrong way

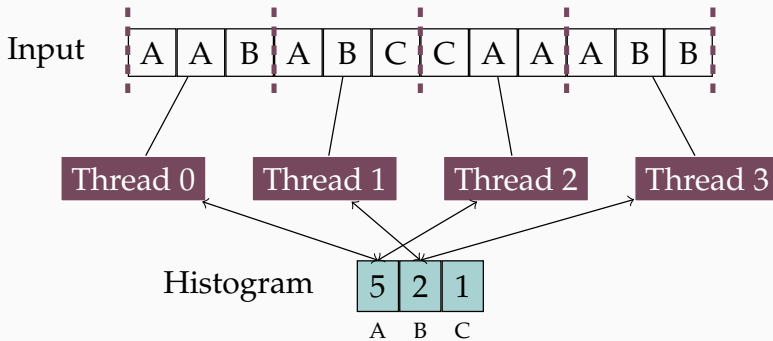
A wrong approach consists in **sectioning** the input, i.e. assigning a chunk of the input to each thread.



What is the issue?

## The very wrong way

A wrong approach consists in **sectioning** the input, i.e. assigning a chunk of the input to each thread.



What is the issue?

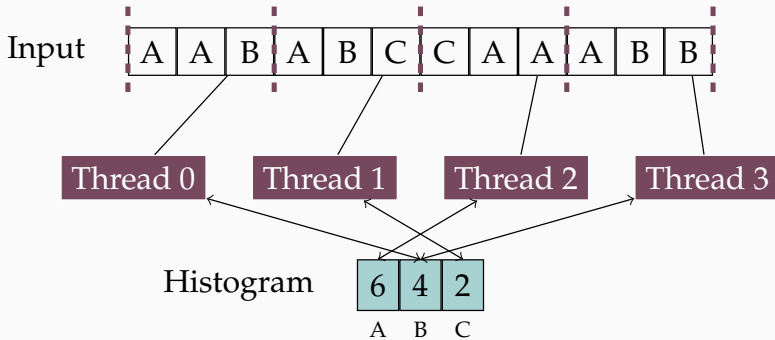
Inefficient, **non-coalesced** memory access.

- Does not leverage cache
- Does not make use of full RAM burst



## The very wrong way

A wrong approach consists in **sectioning** the input, i.e. assigning a chunk of the input to each thread.



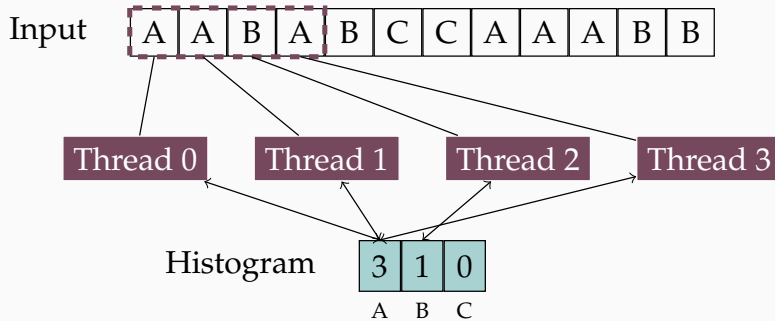
What is the issue?

Inefficient, **non-coalesced** memory access.

- Does not leverage cache
- Does not make use of full RAM burst

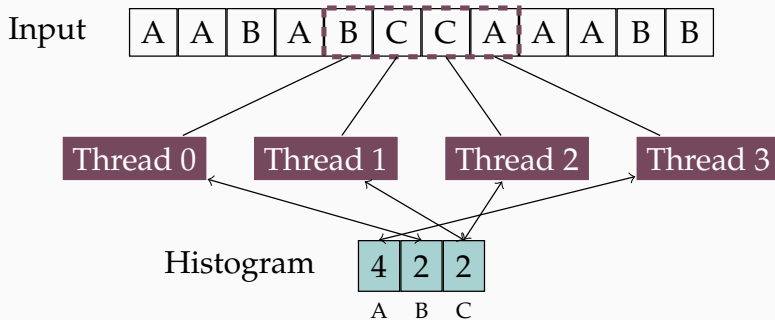
## Interleaved partitioning of input

This enables coalesced memory accesses.



## Interleaved partitioning of input

This enables coalesced memory accesses.



Much more efficient, **coalesced** memory access.

- All threads process a contiguous section of elements
- They all move to the next section and repeat

## First code sample

```
__global__ void histo(int* buf, int w, int h, int pitch, int hist_size, int* hist)
{
    int x = blockDim.x * blockIdx.x + threadIdx.x;
    int y = blockDim.y * blockIdx.y + threadIdx.y;
    if (x >= w || y >= h) return;
    int cellValue = getValue(buf, x, y, pitch);
    hist[cellValue]++; // This is wrong!
}
```

What is the issue?

## First code sample

```
__global__ void histo(int* buf, int w, int h, int pitch, int hist_size, int* hist)
{
    int x = blockDim.x * blockIdx.x + threadIdx.x;
    int y = blockDim.y * blockIdx.y + threadIdx.y;
    if (x >= w || y >= h) return;
    int cellValue = getValue(buf, x, y, pitch);
    hist[cellValue]++; // This is wrong!
}
```

What is the issue?

Data race!

## A correct naive version

```
__global__ void histo(int* buf, int w, int h, int pitch, int hist_size, int* hist)
{
    int x = blockDim.x * blockIdx.x + threadIdx.x;
    int y = blockDim.y * blockIdx.y + threadIdx.y;
    if (x >= w || y >= h) return;
    int cellValue = getValue(buf, x, y, pitch);
    atomicAdd(&hist[cellValue], 1);
}
```

## Parallel algorithm using output privatization

---

A simple solution called “**output privatization**” works by proceeding in two steps:

1. compute a local histogram for each block in shared memory  
*cost to read and write: 1 cycle each*
2. at the end of the block, flush each local histogram to global memory



## Local histogram: initialization

Shared memory must be initialized.

This can be done with the “comb-like” pattern.

```
__global__ void histo(int* buf, int w, int h, int pitch, int hist_size, int* hist)
{
    extern __shared__ int localHist[];
    // linear thread id and block dim to init the 1D histogram
    int i = blockDim.x * threadIdx.y + threadIdx.x;
    int bs = blockDim.x * blockDim.y;
    for (; i < hist_size; i+=bs)
        localHist[i] = 0;
    // Wait for all block's threads before next stage
    __syncthreads();
}
```

Warning: we need synchronization after this stage.

## Local histogram: computation

Like previous code, but with local atomics!

```
__global__ void histo(int* buf, int w, int h, int pitch, int hist_size, int* hist)
{
    // ...

    int x = blockDim.x * blockIdx.x + threadIdx.x;
    int y = blockDim.y * blockIdx.y + threadIdx.y;
    if (x >= w || y >= h) return;
    int cellValue = getValue(buf, x, y, pitch);
    atomicAdd(&(localHist[cellValue]), 1);
    // Wait for all block's threads before next stage
    __syncthreads();
}
```

Warning: we need synchronization after this stage.

## Local histogram: commit to global memory

It is the same pattern as for the initialization.

We use a global atomic here.

```
__global__ void histo(int* buf, int w, int h, int pitch, int hist_size, int* hist)
{
    // ...

    // linear thread id and block dim to copy the 1D histogram
    int i = blockDim.x * threadIdx.y + threadIdx.x;
    int bs = blockDim.x * blockDim.y;
    for (; i < hist_size; i+=bs)
        atomicAdd(&(hist[i]), localHist[i]);
}
```

## Summary

---

Performance boosters:

- coalesced accesses
- output privatization
- (not seen here: cascading?)

Requirements:

- atomics
- synchronization

Limitations:

- histograms smaller than the size of the shared memory
- overhead to allocate and initialize private copies, then commit them to global memory