Global Snapshot

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https://www.lrde.epita.fr/~renault/teaching/algorep/

Why recording the global state of a distributed system is important?

- Check-pointing and recovery if the system fails, it can start start up from a meaningful state
- Monitoring and Debugging
- Termination or Deadlock detection

Problem Statement 2/2

Problem

- No global clock
- No shared memory
- Unpredictable message delays

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How to achieve this snapshot?





Snapshot for non-FIFO channels

- Lai Yang Algorithm
- Mattern's Algorithm

Global State

The global state of a distributed system is a collection of the local states of the processes and the channels.

Let us denote by :

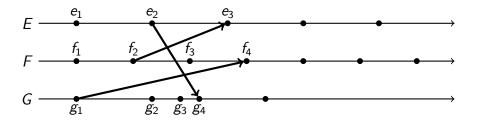
- *LS_i* the local state of state *i*
- *SC_{i,j}* denotes the state of the channel *C_{i,j}*

Global State (formally)

$$GS = \{ \bigcup_{i} LS_{i}, \bigcup_{i,j} SC_{ij} \}$$

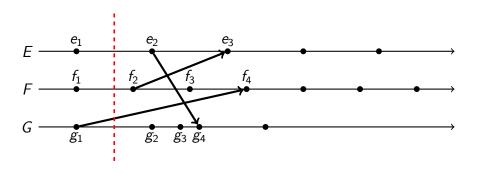
Cuts

A cut in a time diagram is a line joining an arbitrary point on each process line that slices the space-time diagram into a PAST and a FUTURE.



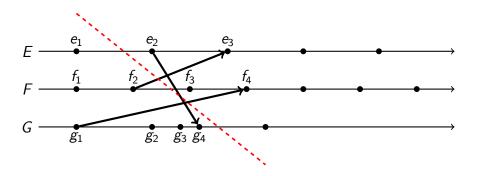
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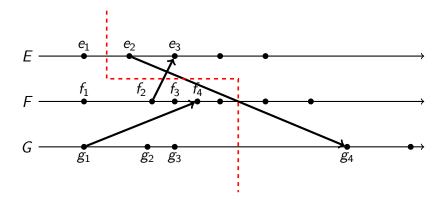
A consistent global State must satisfy the two following rules : **C1** : A send implies that the reception is in progress

$$send(m_{i,j}) \in LS_i \implies m_{i,j} \in SC_{i,j} \otimes rec(m_{i,j}) \in LS_j$$

(\otimes is Ex-OR operator)

• C2 : A reception implies that the sent is in the global state $send(m_{i,j}) \notin LS_i \implies m_{i,j} \notin SC_{i,j} \land rec(m_{i,j}) \notin LS_j$

Consistent Cut



Issues in recording a global state

How to distinguish between the messages to be recorded in the snapshot from those not to be recorded?

• Should respect rules C1 and C2

How to determine the instant when a process takes its snapshot?

 A process p_j must record its snapshot before processing a message m_{ij} that was sent by process p_i after recording its snapshot. Global States and Cuts



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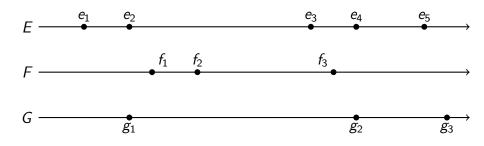
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- The algorithm can be initiated by any process
- The algorithm terminates after each process has received a marker on all of its incoming channels

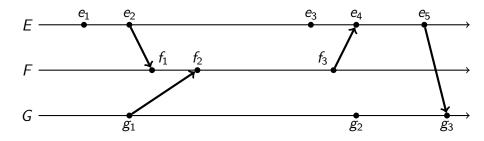
Sending Rule for process *i* :

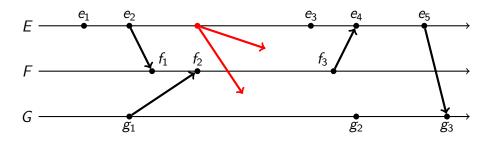
- Process *i* records its state
- For each outgoing channel $C_{i,j}$ on which a marker has not been sent, *i* sends a marker along $C_{i,j}$ before *i* sends further messages along $C_{i,j}$

Receiving Rule for process j:

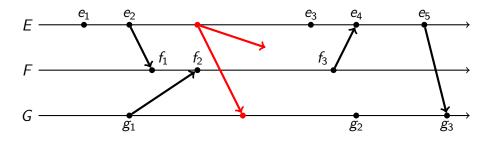
- On receiving a marker along channel $C_{i,j}$:
- if j has not recorded its state then
 - Record the state of C_i, j as the empty set
 - Follow the "Marker Sending Rule"
- else
 - ► Record the state of C_{i,j} as the set of messages received along C_{i,j} after j's state was recorded and before j received the marker along C_{i,j}.



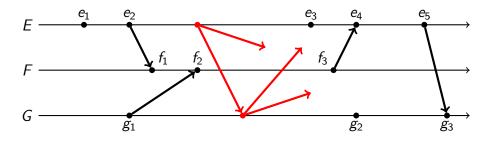




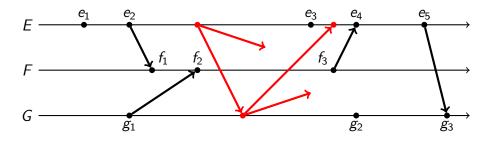
Afer e_2 E decide to take a snapshot. E record local state S_E Send marker through channels C_{E-F} and C_{E-G} (start recording channels status)



G receive marker from E G record local state S_G G record channel C_{E-G} as empty Message to E-F is still in transit.

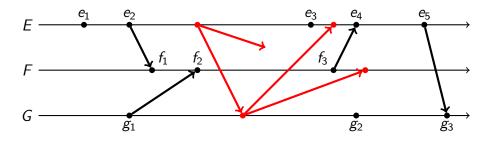


G send marker through channels C_{G-E} and C_{G-F}



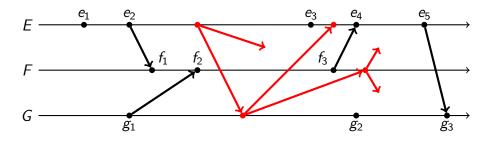
Marker received by E

Duplicate marker : stop recording state of channel C_{E-G} and record it as empty.

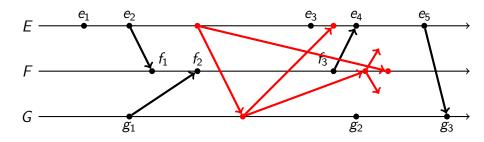


Marker received by F

- F record local state S_F
- F record channel C_{G-F} as empty

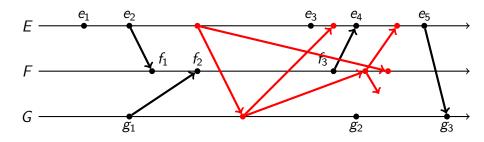


Send marker through channels C_{F-E} and C_{F-G}

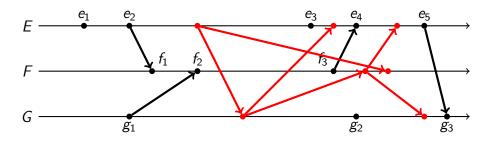


Marker received by F

Duplicate marker : stop recording state of channel C_{E-F} and record it as empty.



Marker received by E Duplicate marker : stop recording state of channel C_{F-E} Record it with message (f_3-e_4) .



Marker received by G Duplicate marker : stop recording state of channel C_{F-G}

Correctness

• When a process j receives message $m_{i,j}$ that precedes the marker on channel $C_{i,j}$: If j has not taken its snapshot yet, then it includes $m_{i,j}$ in its recorded snapshot. Otherwise, it records $m_{i,j}$ in the state of the channel $C_{i,j}$. Thus, condition C1 is satisfied.

• Due to FIFO property of channels, no message sent after the marker on that channel is recorded in the channel state. Thus, condition C2 is satisfied

Complexity

Message Complexity

O(e) for the record of a single instance of the algorithm, with e the number of edges in the graph

Time Complexity O(d) time with d the diameter of the graph

Remarks

• The recorded global state may not correspond to any of the global states that occurred during the computation

BUT...

- The recorded global state may not correspond to any of the global states that occurred during the computation
- The recorded global state is a valid state in an equivalent execution





Snapshot for non-FIFO channels

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Problem

A marker cannot be used to delineate messages into those to be recorded in the global state from those not to be recorded in the global state

Either some degree of inhibition or piggybacking of control information on computation messages to capture out-of-sequence messages.





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- Every message sent by a white/red process is colored white/red
 - White : a message that was sent before the sender of that message recorded its local snapshot
 - Red : a message that was sent after the sender of that message recorded its local snapshot
- Every white process takes its snapshot at its convenience, but no later than the instant it receives a red message.

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- When a process turns red, it sends these histories along with its snapshot to the initiator process that collects the global snapshot
- The initiator process evaluates *transit*(*LS_i*, *LS_j*) to compute the state of a channel *C_{i,j}*

$$SC_{i,j} = \{send(m_{i,j}) \mid send(m_{i,j}) \in LS_i\} \ - \{rec(m_{i,j}) \mid rec(m_{i,j}) \in LS_j\}.$$

Example





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Based on vector clocks and assumes a single initiator process.

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- The initiator "ticks" its local clock and selects a future vector time T at which it would like a global snapshot to be recorded.
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- When a process receives the broadcast, it remembers the value T and returns an acknowledgement to the initiator.

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- Solution The receipt of this dummy message forces each recipient to increase its clock to a value ≥ T if not already ≥ T.
- Each process takes a local snapshot and sends it to the initiator when (just before) its clock increases from a value less than T to a value $\geq T$
- The state of $C_{i,j}$ is all messages sent along $C_{i,j}$ whose timestamp is smaller than T and which are received by j after recording LS_j .

Mattern's Algorithm for non-FIFO channels

Messages sent before the snapshot are white, red otherwise.

- Each process i keeps a counter *cpt_i* that indicates the difference between the number of white messages it has sent and received before recording its snapshot
- It reports this value to the initiator process along with its snapshot and forwards all white messages, it receives henceforth, to the initiator
- Snapshot collection terminates when the initiator has received $\sum cpti$ number of forwarded white messages

Example